

Phase Transition between Small and Large Field Models of Inflation

Ely D. Kovetz, Tel-Aviv University

Based on:

N. Itzhaki and E. D. Kovetz, “A Phase Transition between Small and Large Field Models of Inflation,” Submitted to Phys Rev D.
[arXiv:hep-th/0810.4299]

N. Itzhaki and E. D. Kovetz, “Inflection Point Inflation and Time Dependent Potentials in String Theory,” JHEP 1007, 054 (2007)
[arXiv:hep-th/0708.2798]

Outline

Outline

- The inflationary paradigm - reminder

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Outline

- **The inflationary paradigm - reminder**
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Inflation - The Missing Ingredient

"The earth could have been the size of a pea, so if it's flat over all of New Jersey it's unlikely to get curved in the next couple of miles."

J. Richard Gott III

Inflation - The Missing Ingredient

"The earth could have been the size of a pea, so if it's flat over all of New Jersey it's unlikely to get curved in the next couple of miles."

J. Richard Gott III

- Motivation

Inflation - The Missing Ingredient

"The earth could have been the size of a pea, so if it's flat over all of New Jersey it's unlikely to get curved in the next couple of miles."

J. Richard Gott III

- Motivation
 - The Flatness Problem
 - The Horizon Problem
 - The Relic Abundance Problem
 - The Fluctuations in the CMB Radiation

Inflation - The Missing Ingredient

"The earth could have been the size of a pea, so if it's flat over all of New Jersey it's unlikely to get curved in the next couple of miles."

J. Richard Gott III

- Motivation
 - The Flatness Problem
 - The Horizon Problem
 - The Relic Abundance Problem
 - The Fluctuations in the CMB Radiation

- Solution

Inflation - The Missing Ingredient

"The earth could have been the size of a pea, so if it's flat over all of New Jersey it's unlikely to get curved in the next couple of miles."

J. Richard Gott III

- Motivation

- The Flatness Problem
- The Horizon Problem
- The Relic Abundance Problem
- The Fluctuations in the CMB Radiation

- Solution

A period of accelerated expansion follows shortly after the big-bang. Consequently, the Universe is flattened, the Hubble Radius is shrunked, Relics are heavily diluted and quantum fluctuations are imprinted onto the CMB.

Scalar Field Inflation

Scalar Field Inflation

- The equations of motion for the scalar field (inflaton) driving inflation are:

$$H^2 = \frac{1}{3} \left(\frac{1}{2} \dot{\phi}^2 + V(\phi) \right)$$

$$\ddot{\phi} = -3H\dot{\phi} - V'(\phi)$$

Scalar Field Inflation

- The equations of motion for the scalar field (inflaton) driving inflation are:

$$H^2 = \frac{1}{3} \left(\frac{1}{2} \dot{\phi}^2 + V(\phi) \right)$$

$$\ddot{\phi} = -3H\dot{\phi} - V'(\phi)$$

- where $H = \frac{\dot{a}}{a}$ ($a(t)$ is the scale factor in the metric) and $V(\phi)$ is the potential.

Scalar Field Inflation

- The equations of motion for the scalar field (inflaton) driving inflation are:

$$H^2 = \frac{1}{3} \left(\frac{1}{2} \dot{\phi}^2 + V(\phi) \right)$$

$$\ddot{\phi} = -3H\dot{\phi} - V'(\phi)$$

- where $H = \frac{\dot{a}}{a}$ ($a(t)$ is the scale factor in the metric) and $V(\phi)$ is the potential.

- Inflation takes place if the following parameters:

$$\epsilon(\phi) = \frac{1}{2} \left(\frac{V'}{V} \right)^2 ; \quad \eta(\phi) = \frac{V''}{V}$$

Scalar Field Inflation

- The equations of motion for the scalar field (inflaton) driving inflation are:

$$H^2 = \frac{1}{3} \left(\frac{1}{2} \dot{\phi}^2 + V(\phi) \right)$$

$$\ddot{\phi} = -3H\dot{\phi} - V'(\phi)$$

- where $H = \frac{\dot{a}}{a}$ ($a(t)$ is the scale factor in the metric) and $V(\phi)$ is the potential.

- Inflation takes place if the following parameters:

$$\epsilon(\phi) = \frac{1}{2} \left(\frac{V'}{V} \right)^2 ; \quad \eta(\phi) = \frac{V''}{V}$$

satisfy:

$$\epsilon \ll 1 \quad ; \quad \eta \ll 1$$

Scalar Field Inflation

- The equations of motion for the scalar field (inflaton) driving inflation are:

$$H^2 = \frac{1}{3} \left(\frac{1}{2} \dot{\phi}^2 + V(\phi) \right)$$

$$\ddot{\phi} = -3H\dot{\phi} - V'(\phi)$$

- where $H = \frac{\dot{a}}{a}$ ($a(t)$ is the scale factor in the metric) and $V(\phi)$ is the potential.

- Inflation takes place if the following parameters:

$$\epsilon(\phi) = \frac{1}{2} \left(\frac{V'}{V} \right)^2 ; \quad \eta(\phi) = \frac{V''}{V}$$

satisfy:

$$\epsilon \ll 1 ; \quad \eta \ll 1$$

- We measure the amount of inflation in the slow roll region by counting the number of e-foldings in the growth of the scale factor:

$$N = \ln \frac{a(t_f)}{a(t_i)} = \int_{t_i}^{t_f} H dt$$

Spectral Index and Gravity Waves

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t) .$$

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t) .$$

It is common to describe it statistically via the correlations between density fluctuations at two different points in space. The corresponding two-point correlation in Fourier space is called the "power spectrum" and is given by:

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t).$$

It is common to describe it statistically via the correlations between density fluctuations at two different points in space. The corresponding two-point correlation in Fourier space is called the "power spectrum" and is given by:

$$P_s(k) = A_s (k/k_\star)^{n_s - 1}$$

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t).$$

It is common to describe it statistically via the correlations between density fluctuations at two different points in space. The corresponding two-point correlation in Fourier space is called the "power spectrum" and is given by:

$$P_s(k) = A_s (k/k_\star)^{n_s - 1}$$

- General relativity predicts the existence of a stochastic background of gravitational waves which are fluctuations in the metric, parametrized by:

$$h_{ij}(t, \mathbf{x}) = g_{ij}(t, \mathbf{x}) - \bar{g}_{ij}(t)$$

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t).$$

It is common to describe it statistically via the correlations between density fluctuations at two different points in space. The corresponding two-point correlation in Fourier space is called the "power spectrum" and is given by:

$$P_s(k) = A_s (k/k_\star)^{n_s - 1}$$

- General relativity predicts the existence of a stochastic background of gravitational waves which are fluctuations in the metric, parametrized by:

$$h_{ij}(t, \mathbf{x}) = g_{ij}(t, \mathbf{x}) - \bar{g}_{ij}(t)$$

- And the corresponding power spectrum is then given by:

$$P_t(k) = A_t (k/k_\star)^{n_t}$$

Spectral Index and Gravity Waves

- The existence of structure proves that the universe is not perfectly homogeneous. These inhomogeneities can be parameterized as spatial fluctuations in the density relative to the homogeneous background density:

$$\delta\rho(t, \mathbf{x}) \equiv \rho(t, \mathbf{x}) - \bar{\rho}(t).$$

It is common to describe it statistically via the correlations between density fluctuations at two different points in space. The corresponding two-point correlation in Fourier space is called the "power spectrum" and is given by:

$$P_s(k) = A_s (k/k_\star)^{n_s - 1}$$

- General relativity predicts the existence of a stochastic background of gravitational waves which are fluctuations in the metric, parametrized by:

$$h_{ij}(t, \mathbf{x}) = g_{ij}(t, \mathbf{x}) - \bar{g}_{ij}(t)$$

- And the corresponding power spectrum is then given by:

$$P_t(k) = A_t (k/k_\star)^{n_t}$$

- The spectral index is: n_s and the tensor-to-scalar ratio is: $r \equiv \frac{P_t}{P_s}$

Outline

- The inflationary paradigm - reminder
- **Large field and small field inflation**
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Categorization of Inflation Models

Categorization of Inflation Models

The categorization is done according to the potential of the canonically normalized scalar field (“inflaton”).

Categorization of Inflation Models

The categorization is done according to the potential of the canonically normalized scalar field (“inflaton”).

- Large Field (I) - potentials in which the slow roll conditions are satisfied over a large distance in field space:

$$\Delta\phi \gg M_{Pl}$$

Categorization of Inflation Models

The categorization is done according to the potential of the canonically normalized scalar field (“inflaton”).

- Large Field (I) - potentials in which the slow roll conditions are satisfied over a large distance in field space:

$$\Delta\phi \gg M_{Pl}$$

- Large Field (II) - potentials with positive curvature at the slow roll region:

$$V'' > 0$$

Categorization of Inflation Models

The categorization is done according to the potential of the canonically normalized scalar field (“inflaton”).

- Large Field (I) - potentials in which the slow roll conditions are satisfied over a large distance in field space:

$$\Delta\phi \gg M_{Pl}$$

- Large Field (II) - potentials with positive curvature at the slow roll region:

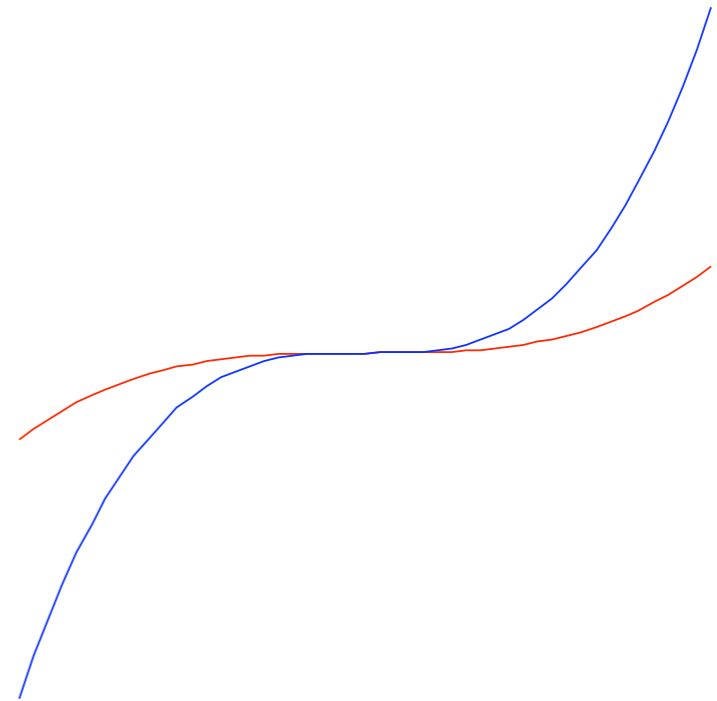
$$V'' > 0$$

These two categorizations, though in some cases complementary, are not equivalent (for example, a recent model in string theory involving a ϕ^α , $\alpha = \frac{2}{3}$ potential (L. McAllister and E. Silverstein, hep-th/0710.2951) will be considered a large field model according to the first categorization, but a small field model according to the second).

Categorization of Inflation Models

Categorization of Inflation Models

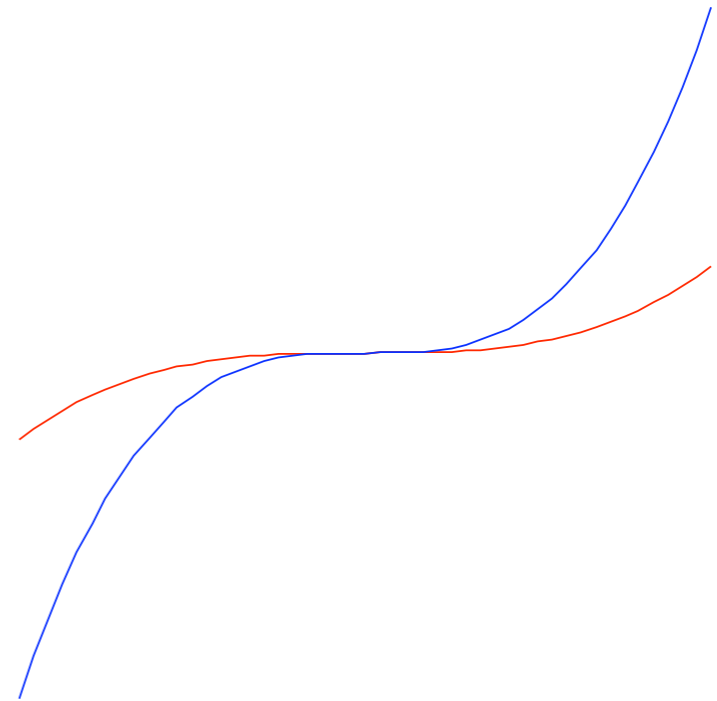
Differences between large field and small field models:



Categorization of Inflation Models

Differences between large field and small field models:

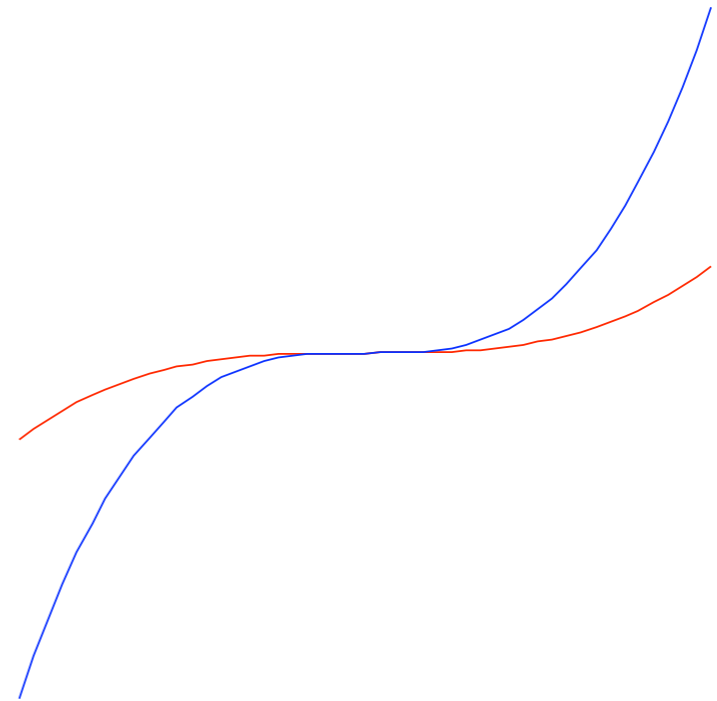
- In large field models the initial conditions have no important role (physical consequences are determined by last e-foldings alone). In small field models, however, they can easily lead to overshooting of the slow roll region.



Categorization of Inflation Models

Differences between large field and small field models:

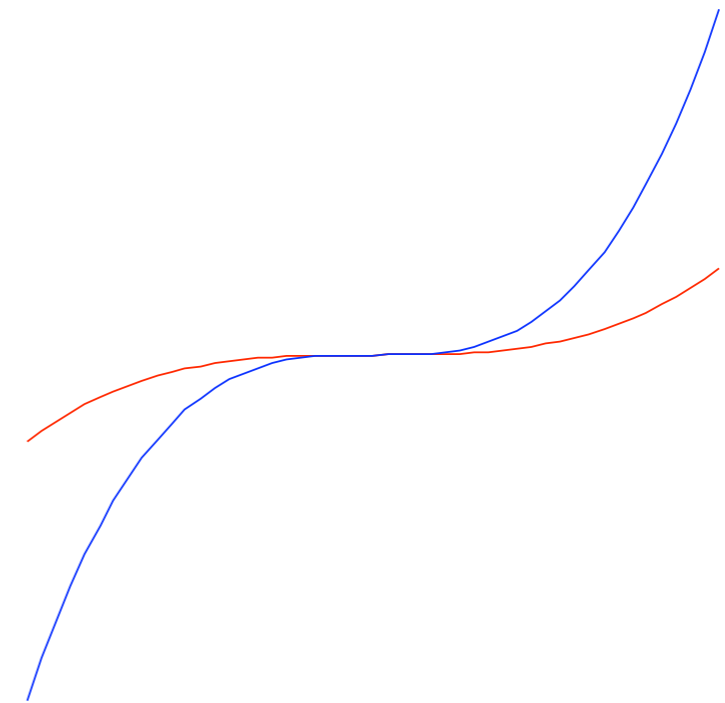
- In large field models the initial conditions have no important role (physical consequences are determined by last e-foldings alone). In small field models, however, they can easily lead to overshooting of the slow roll region.
- Constructing large field models in string theory is quite difficult (as mentioned, this was recently done by Silverstein et. al).



Categorization of Inflation Models

Differences between large field and small field models:

- In large field models the initial conditions have no important role (physical consequences are determined by last e-foldings alone). In small field models, however, they can easily lead to overshooting of the slow roll region.
- Constructing large field models in string theory is quite difficult (as mentioned, this was recently done by Silverstein et. al).



- For single field models of inflation, the tensor-to-scalar ratio and the spectral index are related by:

$$r = \frac{8}{3}(1 - n_s) + \frac{16}{3} \frac{V''}{V}.$$

This means that large field models will be easier to constrain in experiments.

Large-Small Field Phase Transition

Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

- Consider a one-dimensional slice of the space of possible models and rescale (keeping kinetic term canonically normalized):

$$\phi \rightarrow \lambda\phi$$

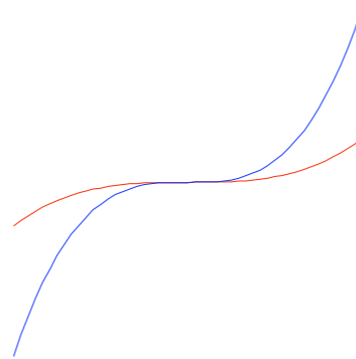
Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

- Consider a one-dimensional slice of the space of possible models and rescale (keeping kinetic term canonically normalized):

$$\phi \rightarrow \lambda\phi$$

- This transformation simply changes the potential, so that:



Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

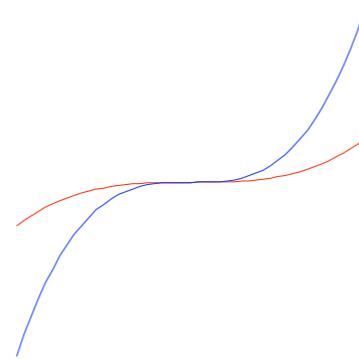
- Consider a one-dimensional slice of the space of possible models and rescale (keeping kinetic term canonically normalized):

$$\phi \rightarrow \lambda\phi$$

- This transformation simply changes the potential, so that:

and we see that:

$$\lambda \rightarrow \infty : \text{Small Field}, \quad \lambda \rightarrow 0 : \text{Large Field}$$



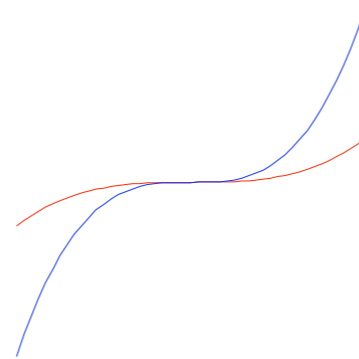
Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

- Consider a one-dimensional slice of the space of possible models and rescale (keeping kinetic term canonically normalized):

$$\phi \rightarrow \lambda\phi$$

- This transformation simply changes the potential, so that:



and we see that:

$$\lambda \rightarrow \infty : \text{Small Field}, \quad \lambda \rightarrow 0 : \text{Large Field}$$

and expect:

$$\lim_{\lambda \rightarrow \infty} N(\lambda) = 0, \quad \lim_{\lambda \rightarrow 0} N(\lambda) = \infty$$

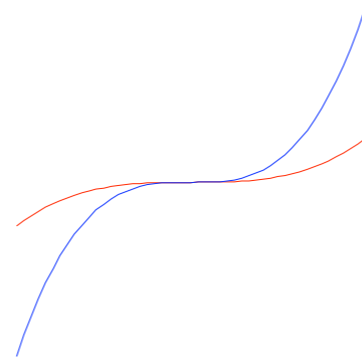
Large-Small Field Phase Transition

If the two models are different, is there a phase transition between them?

- Consider a one-dimensional slice of the space of possible models and rescale (keeping kinetic term canonically normalized):

$$\phi \rightarrow \lambda\phi$$

- This transformation simply changes the potential, so that:



and we see that:

$$\lambda \rightarrow \infty : \text{Small Field}, \quad \lambda \rightarrow 0 : \text{Large Field}$$

and expect:

$$\lim_{\lambda \rightarrow \infty} N(\lambda) = 0, \quad \lim_{\lambda \rightarrow 0} N(\lambda) = \infty$$

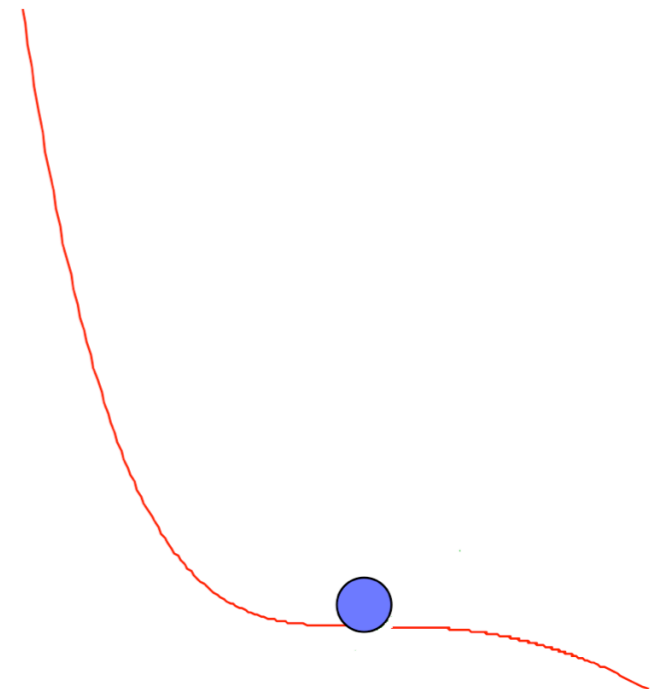
Therefore, N is our candidate for the order parameter.

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- **Inflection point inflation (IPI)**
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Inflection Point Inflation

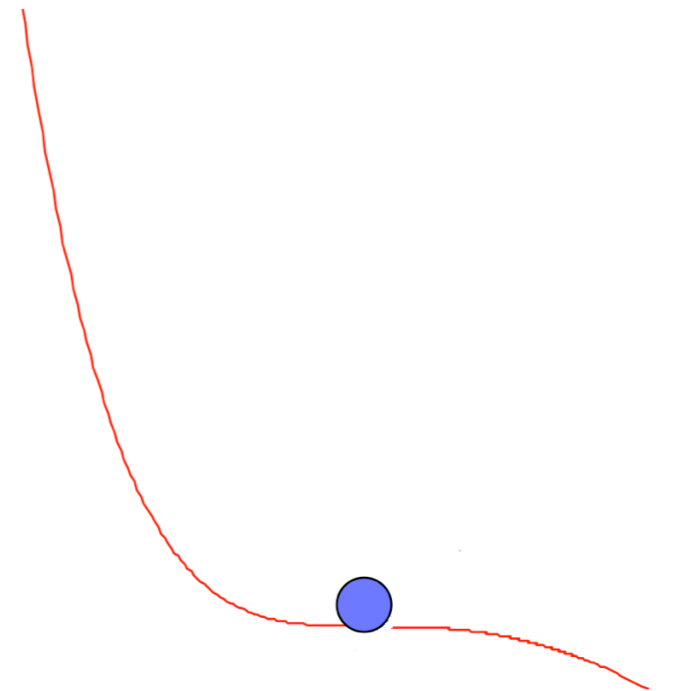
"Inflation comes in several variants: old, new, baroque, decadent and eternal."
Martin Rees



Inflection Point Inflation

"Inflation comes in several variants: old, new, baroque, decadent and eternal."
Martin Rees

Motivation:

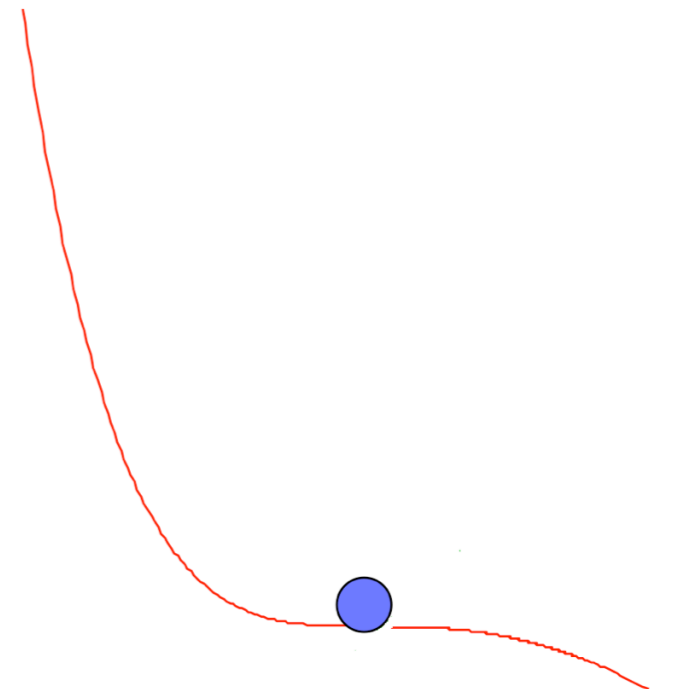


Inflection Point Inflation

"Inflation comes in several variants: old, new, baroque, decadent and eternal."
Martin Rees

Motivation:

- Typical potentials for scalars (moduli) in string theory are not flat enough to generate a long period of inflation.



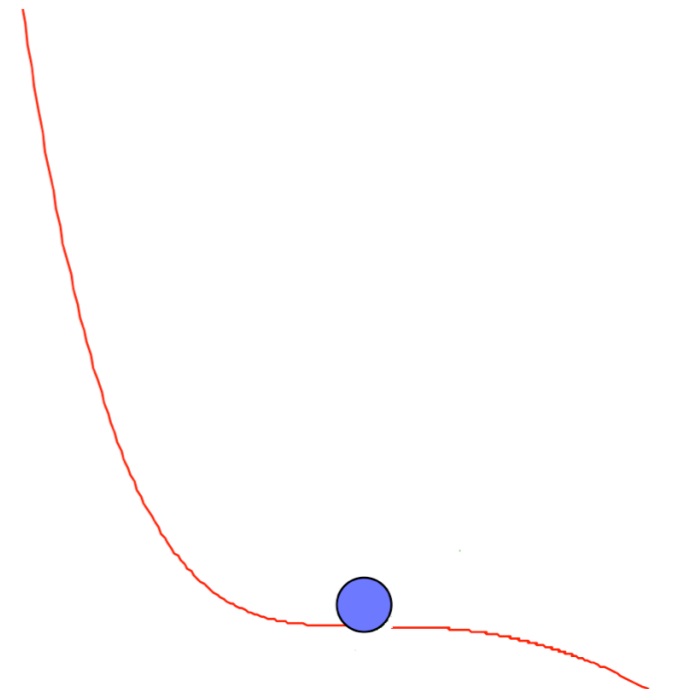
Inflection Point Inflation

"Inflation comes in several variants: old, new, baroque, decadent and eternal."
Martin Rees

Motivation:

- Typical potentials for scalars (moduli) in string theory are not flat enough to generate a long period of inflation.

Solution:



Inflection Point Inflation

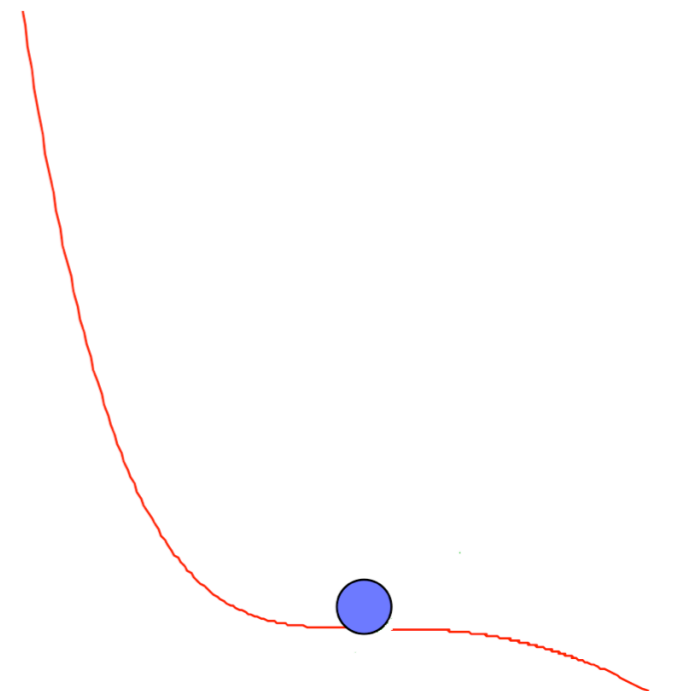
"Inflation comes in several variants: old, new, baroque, decadent and eternal."
Martin Rees

Motivation:

- Typical potentials for scalars (moduli) in string theory are not flat enough to generate a long period of inflation.

Solution:

- If the inflaton potential has an inflection point, then a large amount of inflation will be generated, provided that the inflaton spends enough time in this region.



Inflection Point Inflation

Properties of IPI:

- Can be approximated near the potential by: $V(\phi) = V_0 (1 + \beta\phi^3)$
where without loss of generality we assume that the inflection point is at zero.
- Recently became popular, especially in the context of String Theory.
- Fine-tuning of parameters is required to yield an inflection point.
- Highly sensitive to the initial condition (overshoot problem).

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- **Phase transition (PT) in IPI**
- Generalizations of the PT phenomenon
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Search for a Phase Transition

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

- According to our second categorization:

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

- According to our second categorization:

for any β a model is large field where $\phi > 0$ and small field for $\phi < 0$.

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

- According to our second categorization:

for any β a model is large field where $\phi > 0$ and small field for $\phi < 0$.

- According to our first categorization:

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

- According to our second categorization:

for any β a model is large field where $\phi > 0$ and small field for $\phi < 0$.

- According to our first categorization:

for $\beta \ll 1$ the models are large field and for $\beta \gg 1$ they are small field.

Search for a Phase Transition

Working with the potential in the form: $V(\phi) = V_0 (1 + \beta\phi^3)$

- According to our second categorization:

for any β a model is large field where $\phi > 0$ and small field for $\phi < 0$.

- According to our first categorization:

for $\beta \ll 1$ the models are large field and for $\beta \gg 1$ they are small field.

- To demonstrate the PT property numerically, we notice that taking $\phi \rightarrow \lambda\phi$ and keeping the kinetic term fixed is equivalent to keeping ϕ fixed and transforming: $\beta \rightarrow \lambda^3\beta$. Therefore, we can search for a critical β_c where a PT occurs between large and small field domains.

First Numerical Results

First Numerical Results

- The equations of motion near the inflection point become:

$$\begin{aligned}3H^2 &= \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3) \\ \ddot{\phi} &= -3H\dot{\phi} - 3V_0\beta\phi^2\end{aligned}$$

First Numerical Results

- The equations of motion near the inflection point become:

$$\begin{aligned}3H^2 &= \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3) \\ \ddot{\phi} &= -3H\dot{\phi} - 3V_0\beta\phi^2\end{aligned}$$

- Using the symmetry $V_0 \rightarrow \alpha^2 V_0$, $t \rightarrow t/\alpha$, under which $N = \int H dt$, our order parameter, is invariant, we can fix: $V_0 = 1$.

First Numerical Results

- The equations of motion near the inflection point become:

$$\begin{aligned}3H^2 &= \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3) \\ \ddot{\phi} &= -3H\dot{\phi} - 3V_0\beta\phi^2\end{aligned}$$

- Using the symmetry $V_0 \rightarrow \alpha^2 V_0$, $t \rightarrow t/\alpha$, under which $N = \int H dt$, our order parameter, is invariant, we can fix: $V_0 = 1$.
- Solving for different initial conditions, we get:

First Numerical Results

- The equations of motion near the inflection point become:

$$3H^2 = \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3)$$

$$\ddot{\phi} = -3H\dot{\phi} - 3V_0\beta\phi^2$$

- Using the symmetry $V_0 \rightarrow \alpha^2 V_0$, $t \rightarrow t/\alpha$, under which $N = \int H dt$, our order parameter, is invariant, we can fix: $V_0 = 1$.

- Solving for different initial conditions, we get:

$\beta \setminus \phi_{init}$	0.5	1	5	10	100
0.1	∞	∞	∞	∞	∞
0.7	∞	∞	∞	∞	∞
0.7744	∞	∞	∞	∞	∞
0.7745	∞	∞	38404.9097	38218.5366	38218.5365
0.8	∞	∞	48.3532	48.3529	48.3529
1	∞	∞	5.2579	5.2579	5.2579
5	0.96866	0.46226	0.35061	0.35061	0.35061

First Numerical Results

- The equations of motion near the inflection point become:

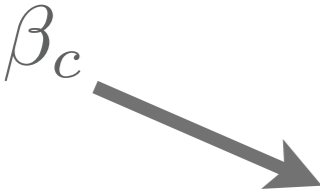
$$3H^2 = \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3)$$

$$\ddot{\phi} = -3H\dot{\phi} - 3V_0\beta\phi^2$$

- Using the symmetry $V_0 \rightarrow \alpha^2 V_0$, $t \rightarrow t/\alpha$, under which $N = \int H dt$, our order parameter, is invariant, we can fix: $V_0 = 1$.

- Solving for different initial conditions, we get:

$\beta \setminus \phi_{init}$	0.5	1	5	10	100
0.1	∞	∞	∞	∞	∞
0.7	∞	∞	∞	∞	∞
0.7744	∞	∞	∞	∞	∞
0.7745	∞	∞	38404.9097	38218.5366	38218.5365
0.8	∞	∞	48.3532	48.3529	48.3529
1	∞	∞	5.2579	5.2579	5.2579
5	0.96866	0.46226	0.35061	0.35061	0.35061

β_c 

First Numerical Results

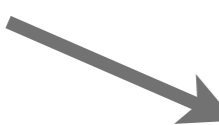
- The equations of motion near the inflection point become:

$$3H^2 = \frac{1}{2}\dot{\phi}^2 + V_0(1 + \beta\phi^3)$$

$$\ddot{\phi} = -3H\dot{\phi} - 3V_0\beta\phi^2$$

- Using the symmetry $V_0 \rightarrow \alpha^2 V_0$, $t \rightarrow t/\alpha$, under which $N = \int H dt$, our order parameter, is invariant, we can fix: $V_0 = 1$.

- Solving for different initial conditions, we get:

β_c 

$\beta \setminus \phi_{init}$	0.5	1	5	10	100
0.1	∞	∞	∞	∞	∞
0.7	∞	∞	∞	∞	∞
0.7744	∞	∞	∞	∞	∞
0.7745	∞	∞	38404.9097	38218.5366	38218.5365
0.8	∞	∞	48.3532	48.3529	48.3529
1	∞	∞	5.2579	5.2579	5.2579
5	0.96866	0.46226	0.35061	0.35061	0.35061

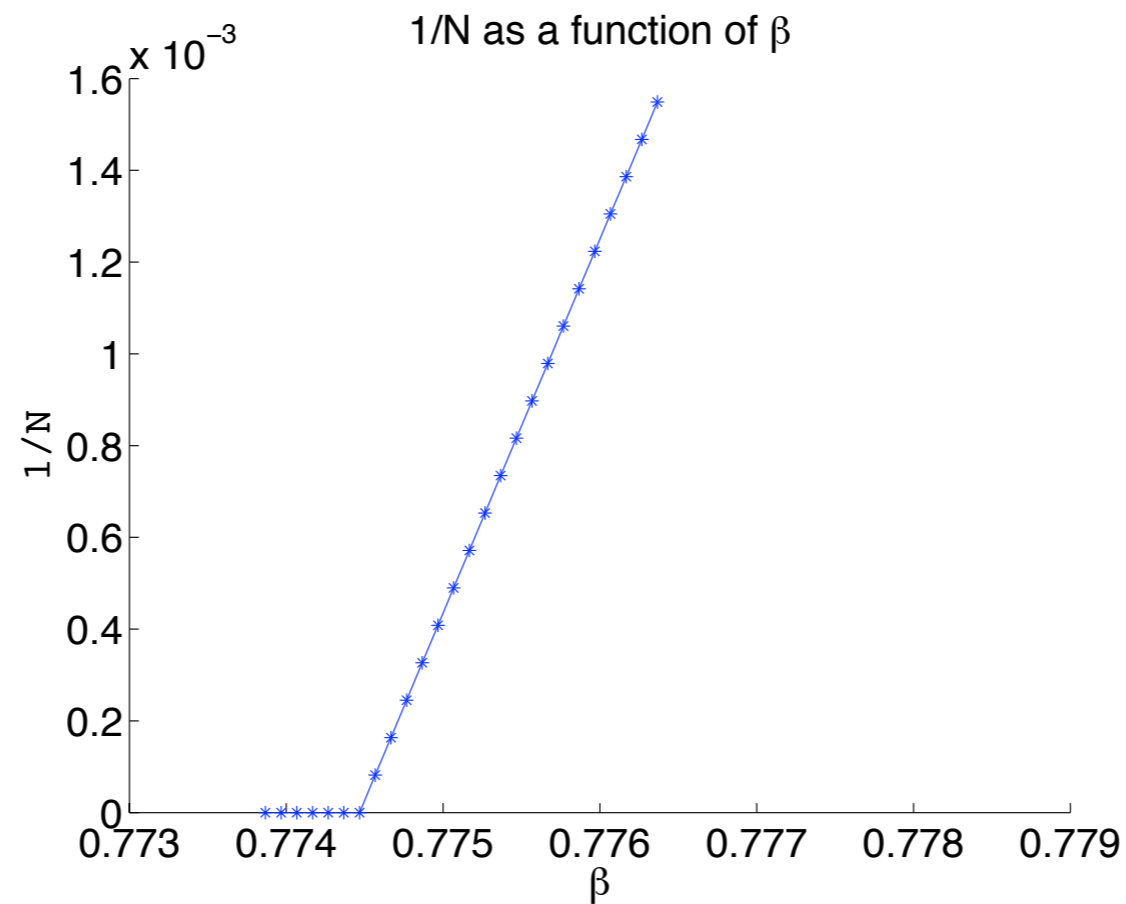
Order Parameter for the PT

Order Parameter for the PT

- The behavior of our order parameter, $1/N_{e-folds}$, is reminiscent of that found in phase transitions of the second kind:

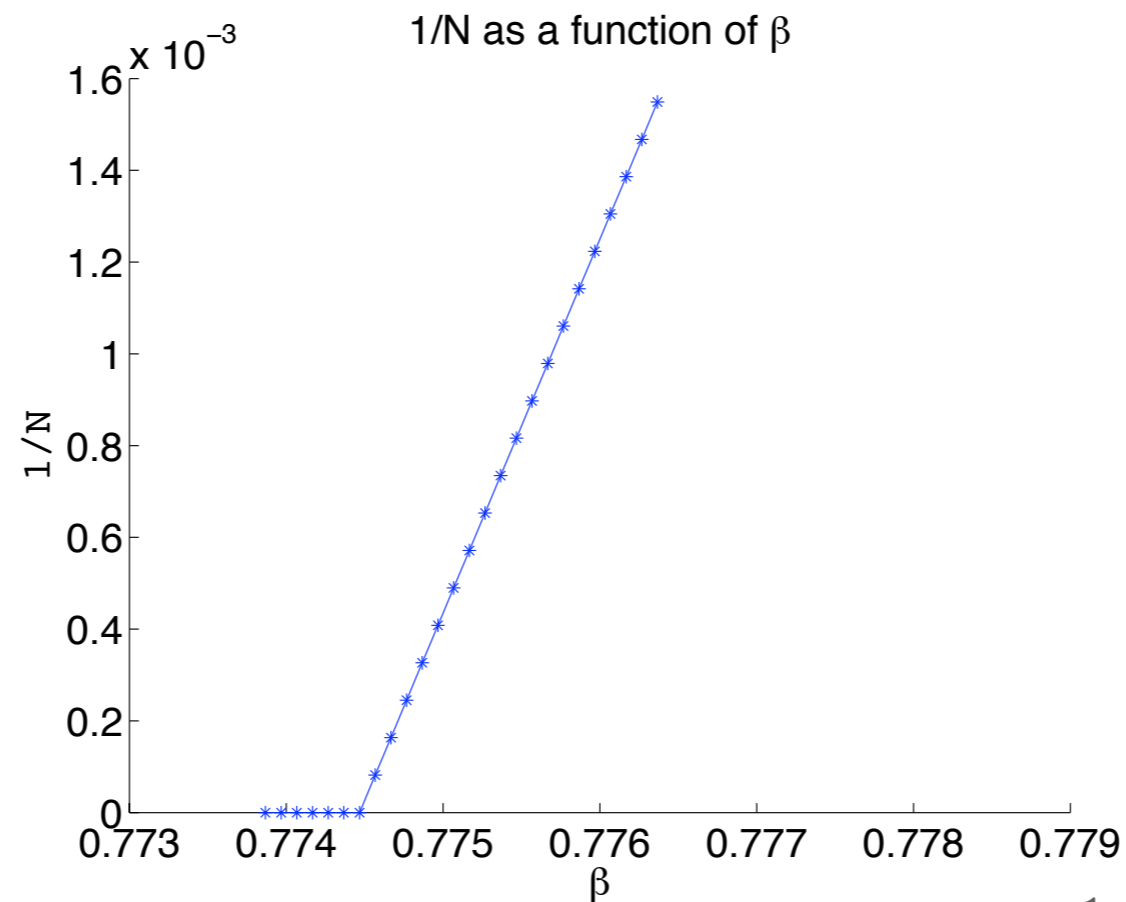
Order Parameter for the PT

- The behavior of our order parameter, $1/N_{e-folds}$, is reminiscent of that found in phase transitions of the second kind:



Order Parameter for the PT

- The behavior of our order parameter, $1/N_{e-folds}$, is reminiscent of that found in phase transitions of the second kind:



- $N_{e-folds}$ is time dependent. An alternative is to use: $\frac{1}{N} \sim \dot{\phi}(\phi = 0) \equiv \dot{\phi}_0$ and identify $\dot{\phi}_0$ as the order parameter.

Scaling Behavior

Scaling Behavior

- Approaching β_c both order parameters exhibit scaling behavior of the form:

Scaling Behavior

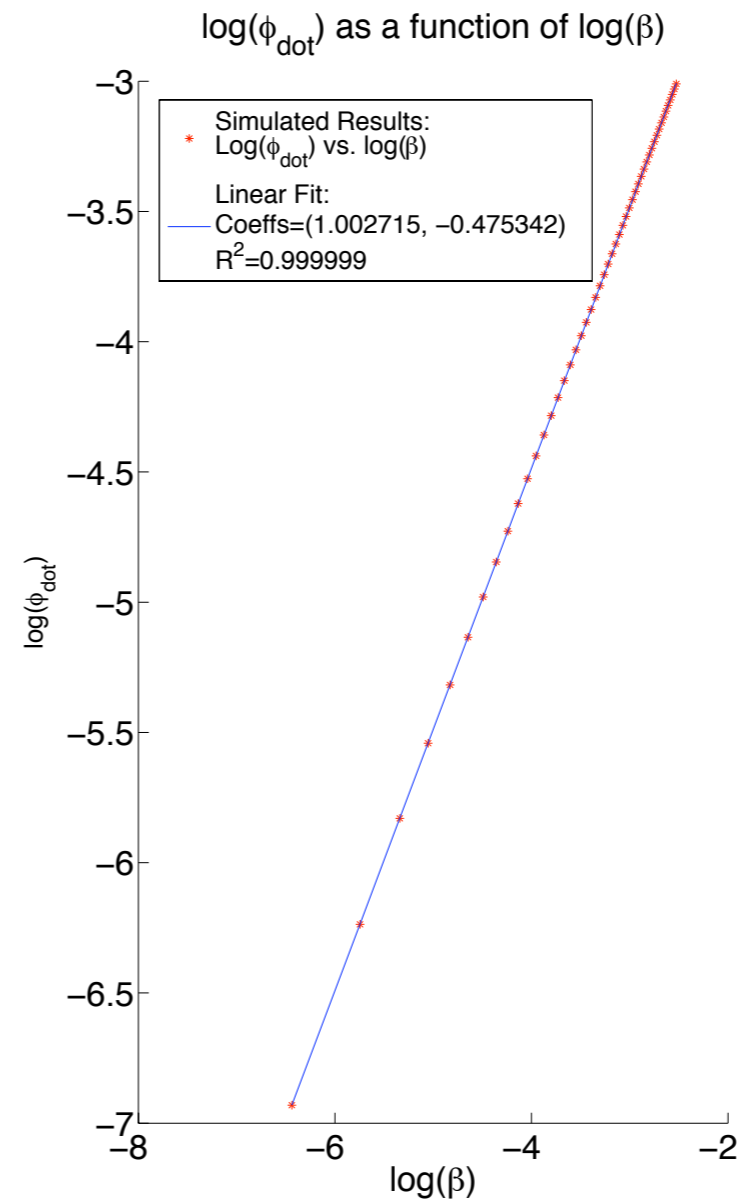
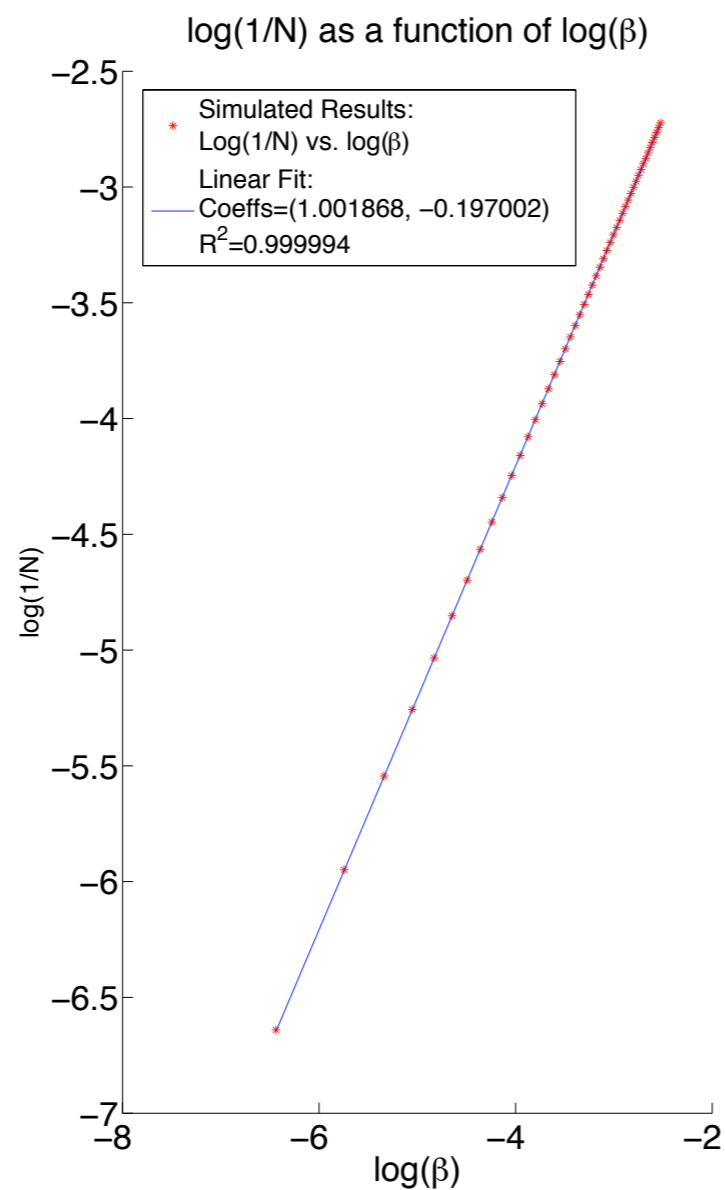
- Approaching β_c both order parameters exhibit scaling behavior of the form:

$$\dot{\phi}_0 \sim \frac{1}{N} \propto (\beta - \beta_c)^1$$

Scaling Behavior

- Approaching β_c both order parameters exhibit scaling behavior of the form:

$$\dot{\phi}_0 \sim \frac{1}{N} \propto (\beta - \beta_c)^1$$



Summing Up

Summing Up

So what have we learned so far?

Summing Up

So what have we learned so far?

- A sudden change occurs at a finite point in the transformation $\phi \rightarrow \lambda\phi$.

Summing Up

So what have we learned so far?

- A sudden change occurs at a finite point in the transformation $\phi \rightarrow \lambda\phi$.
- There is a typical order parameter for this change, namely $\frac{1}{N}$.

Summing Up

So what have we learned so far?

- A sudden change occurs at a finite point in the transformation $\phi \rightarrow \lambda\phi$.
- There is a typical order parameter for this change, namely $\frac{1}{N}$.
- Approaching the critical point, the order parameter scales as the distance from it, according to the following scaling law: $\frac{1}{N} \propto (\lambda - \lambda_c)^\gamma$

Summing Up

So what have we learned so far?

- A sudden change occurs at a finite point in the transformation $\phi \rightarrow \lambda\phi$.
- There is a typical order parameter for this change, namely $\frac{1}{N}$.
- Approaching the critical point, the order parameter scales as the distance from it, according to the following scaling law: $\frac{1}{N} \propto (\lambda - \lambda_c)^\gamma$
- The critical exponent is integer: $\gamma = 1$

Summing Up

So what have we learned so far?

- A sudden change occurs at a finite point in the transformation $\phi \rightarrow \lambda\phi$.
- There is a typical order parameter for this change, namely $\frac{1}{N}$.
- Approaching the critical point, the order parameter scales as the distance from it, according to the following scaling law: $\frac{1}{N} \propto (\lambda - \lambda_c)^\gamma$
- The critical exponent is integer: $\gamma = 1$
- The behavior is universal in the sense that it is independent of initial conditions. This is a direct result of the attractor property of slow roll inflation.

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- **Generalizations of the PT phenomenon**
- Analytic discussion
- Somewhat different PT in a stringy IPI model

Higher Order Terms

Higher Order Terms

What if we consider higher order terms?

Higher Order Terms

What if we consider higher order terms?

- For a potential:
$$V(\phi) = V_0 \left(1 + \beta\phi^3 + \sum_{n_i > 3} \alpha_i \phi^{n_i} \right)$$

Higher Order Terms

What if we consider higher order terms?

- For a potential:
$$V(\phi) = V_0 \left(1 + \beta\phi^3 + \sum_{n_i > 3} \alpha_i \phi^{n_i} \right)$$

the PT under $\phi \rightarrow \lambda\phi$ remains, with the same scaling behavior.

Higher Order Terms

What if we consider higher order terms?

- For a potential:
$$V(\phi) = V_0 \left(1 + \beta\phi^3 + \sum_{n_i > 3} \alpha_i \phi^{n_i} \right)$$

the PT under $\phi \rightarrow \lambda\phi$ remains, with the same scaling behavior.

- However, if $\beta = 0$ and the leading contribution to the potential is
$$(1 + \alpha\phi^{2n+1}), \quad n = 1, 2, \dots$$

Higher Order Terms

What if we consider higher order terms?

- For a potential:
$$V(\phi) = V_0 \left(1 + \beta\phi^3 + \sum_{n_i > 3} \alpha_i \phi^{n_i} \right)$$

the PT under $\phi \rightarrow \lambda\phi$ remains, with the same scaling behavior.

- However, if $\beta = 0$ and the leading contribution to the potential is

$$(1 + \alpha\phi^{2n+1}), \quad n = 1, 2, \dots$$

then the critical exponent is:

$$\gamma = 2n - 1$$

Higher Order Terms

What if we consider higher order terms?

- For a potential: $V(\phi) = V_0 \left(1 + \beta\phi^3 + \sum_{n_i > 3} \alpha_i \phi^{n_i} \right)$

the PT under $\phi \rightarrow \lambda\phi$ remains, with the same scaling behavior.

- However, if $\beta = 0$ and the leading contribution to the potential is $(1 + \alpha\phi^{2n+1})$, $n = 1, 2, \dots$

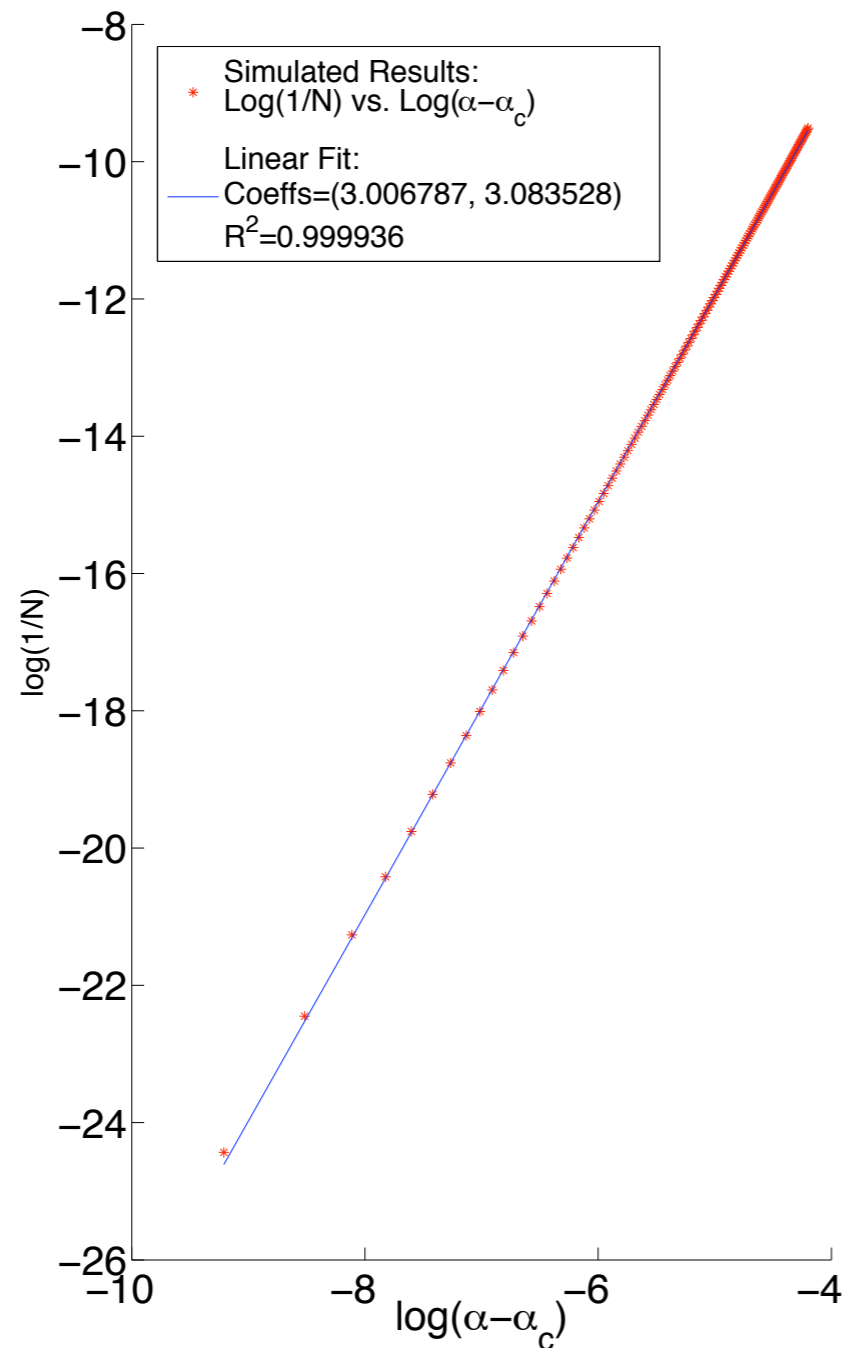
then the critical exponent is:

$$\gamma = 2n - 1$$

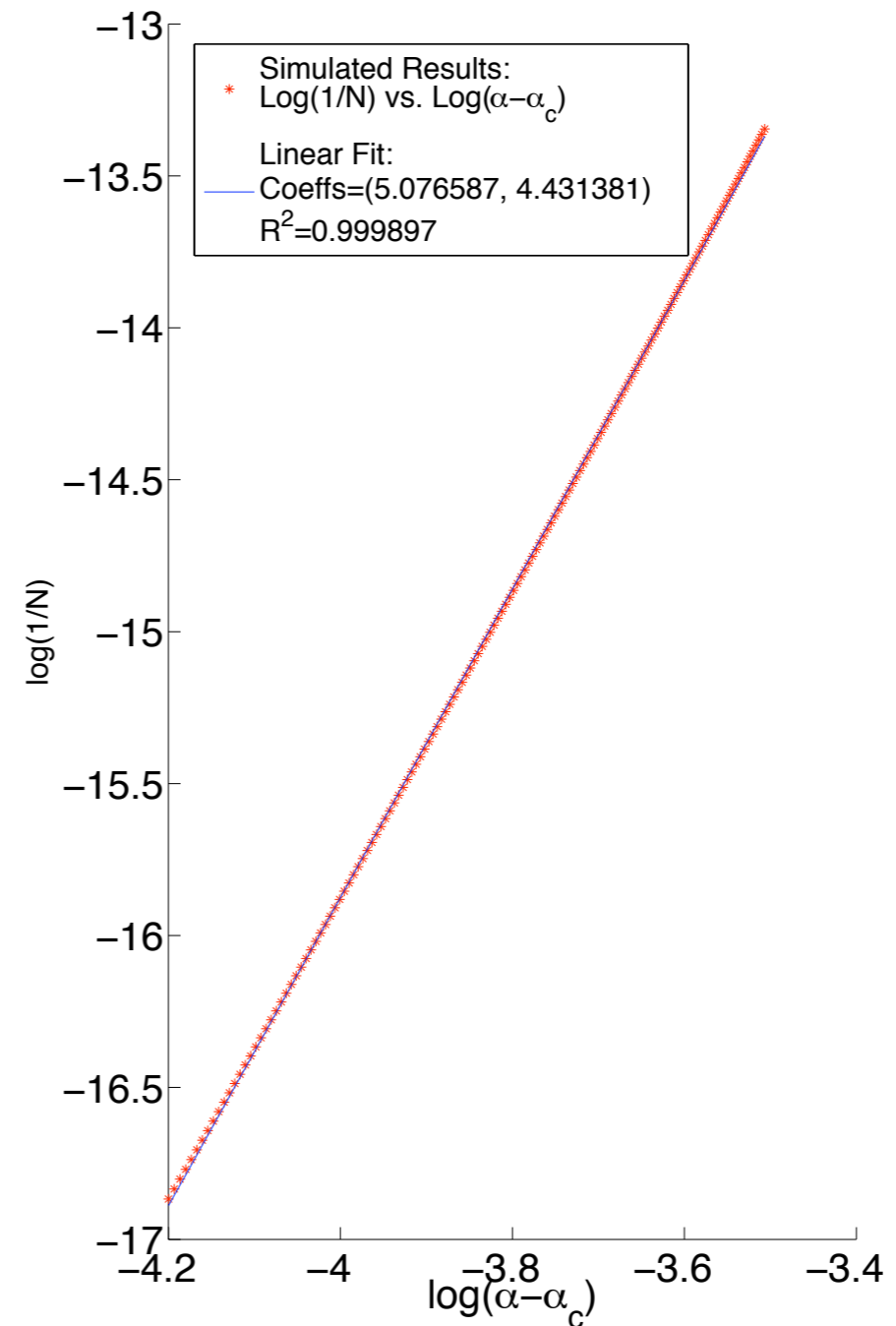
- Potentials in which the lowest non-zero derivative is even exhibit no critical behavior at all.

Different Critical Exponents

Scaling of $1/N$ as a function of $\alpha - \alpha_c$ for $V_0 + \alpha\phi^5$



Scaling of $1/N$ as a function of $\alpha - \alpha_c$ for $V_0 + \alpha\phi^7$



Approximated Inflection Point

Approximated Inflection Point

What if the inflection point in the potential is not exact?

Approximated Inflection Point

What if the inflection point in the potential is not exact?

- For a potential of the form: $V = V_0(1 + \delta\phi + \beta\phi^3)$
there will obviously be no finite λ_c in the transformation $\beta \rightarrow \lambda^3\beta$, $\delta \rightarrow \lambda\delta$
such that $N(\lambda_c) = \infty$.

Approximated Inflection Point

What if the inflection point in the potential is not exact?

- For a potential of the form: $V = V_0(1 + \delta\phi + \beta\phi^3)$
there will obviously be no finite λ_c in the transformation $\beta \rightarrow \lambda^3\beta$, $\delta \rightarrow \lambda\delta$
such that $N(\lambda_c) = \infty$.
- In such a case it can be shown that there is an upper bound on N :
(Baumann et al, hep-th/0706.0360)

Approximated Inflection Point

What if the inflection point in the potential is not exact?

- For a potential of the form: $V = V_0(1 + \delta\phi + \beta\phi^3)$
there will obviously be no finite λ_c in the transformation $\beta \rightarrow \lambda^3\beta$, $\delta \rightarrow \lambda\delta$
such that $N(\lambda_c) = \infty$.

- In such a case it can be shown that there is an upper bound on N :
(Baumann et al, hep-th/0706.0360)

$$N_{max} = \pi(3\delta\beta)^{-1/2}$$

Approximated Inflection Point

What if the inflection point in the potential is not exact?

- For a potential of the form: $V = V_0(1 + \delta\phi + \beta\phi^3)$ there will obviously be no finite λ_c in the transformation $\beta \rightarrow \lambda^3\beta$, $\delta \rightarrow \lambda\delta$ such that $N(\lambda_c) = \infty$.

- In such a case it can be shown that there is an upper bound on N :
(Baumann et al, hep-th/0706.0360)

$$N_{max} = \pi(3\delta\beta)^{-1/2}$$

- We find that for $\delta \neq 0$ there is a λ_c such that:
 - For $\lambda > \lambda_c$ the amount of inflation depends on the initial condition. Then, in order to maximize N we have to fine tune the initial condition.
 - For $\lambda < \lambda_c$, however, any non-singular initial condition gives $N = N_{max}$.

Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- **Analytic discussion**
- Somewhat different PT in a stringy IPI model

Simplifying the Equations

Simplifying the Equations

We make the following approximations:

Simplifying the Equations

We make the following approximations:

- Near the critical point the inflaton spends most of the time near the inflection point where H is constant, which leaves us with:

$$\ddot{\phi} = -3H_0\dot{\phi} - 3V_0\beta\phi^2, \quad \text{with} \quad 3H_0^2 = V_0$$

Simplifying the Equations

We make the following approximations:

- Near the critical point the inflaton spends most of the time near the inflection point where H is constant, which leaves us with:

$$\ddot{\phi} = -3H_0\dot{\phi} - 3V_0\beta\phi^2, \quad \text{with} \quad 3H_0^2 = V_0$$

choosing $H = 1/3$ (using the symmetry we used above to set V_0), we get:

$$\ddot{\phi} = -\dot{\phi} - \beta\phi^2$$

Simplifying the Equations

We make the following approximations:

- Near the critical point the inflaton spends most of the time near the inflection point where H is constant, which leaves us with:

$$\ddot{\phi} = -3H_0\dot{\phi} - 3V_0\beta\phi^2, \quad \text{with} \quad 3H_0^2 = V_0$$

choosing $H = 1/3$ (using the symmetry we used above to set V_0), we get:

$$\ddot{\phi} = -\dot{\phi} - \beta\phi^2$$

- This is invariant under: $\phi \rightarrow C\phi, \quad \beta \rightarrow \beta/C^2$

Using a Different Order Parameter

Using a Different Order Parameter

- so if the solutions start with $\phi(0) = \phi_0$ and $\dot{\phi}(0) = 0$, then $\phi_0^2\beta$ can be used to parametrize them. Therefore, we can either fix β and vary the initial condition, or vary the initial condition with β fixed.

Using a Different Order Parameter

- so if the solutions start with $\phi(0) = \phi_0$ and $\dot{\phi}(0) = 0$, then $\phi_0^2\beta$ can be used to parametrize them. Therefore, we can either fix β and vary the initial condition, or vary the initial condition with β fixed.
- We shall fix $\beta = 1$ and vary the initial condition to look for a phase transition. We remain with:

Using a Different Order Parameter

- so if the solutions start with $\phi(0) = \phi_0$ and $\dot{\phi}(0) = 0$, then $\phi_0^2 \beta$ can be used to parametrize them. Therefore, we can either fix β and vary the initial condition, or vary the initial condition with β fixed.
- We shall fix $\beta = 1$ and vary the initial condition to look for a phase transition. We remain with:

$$\ddot{\phi} = -\dot{\phi} - \phi^2$$

Using a Different Order Parameter

- so if the solutions start with $\phi(0) = \phi_0$ and $\dot{\phi}(0) = 0$, then $\phi_0^2 \beta$ can be used to parametrize them. Therefore, we can either fix β and vary the initial condition, or vary the initial condition with β fixed.
- We shall fix $\beta = 1$ and vary the initial condition to look for a phase transition. We remain with:

$$\ddot{\phi} = -\dot{\phi} - \phi^2$$

- Since:
$$N_{e-folds} = \int_{end}^{start} H dt \sim H_{inflc} \int_{end}^{start} dt = \frac{1}{3} (t_{end} - t_{start})$$

Using a Different Order Parameter

- so if the solutions start with $\phi(0) = \phi_0$ and $\dot{\phi}(0) = 0$, then $\phi_0^2 \beta$ can be used to parametrize them. Therefore, we can either fix β and vary the initial condition, or vary the initial condition with β fixed.
- We shall fix $\beta = 1$ and vary the initial condition to look for a phase transition. We remain with:

$$\ddot{\phi} = -\dot{\phi} - \phi^2$$

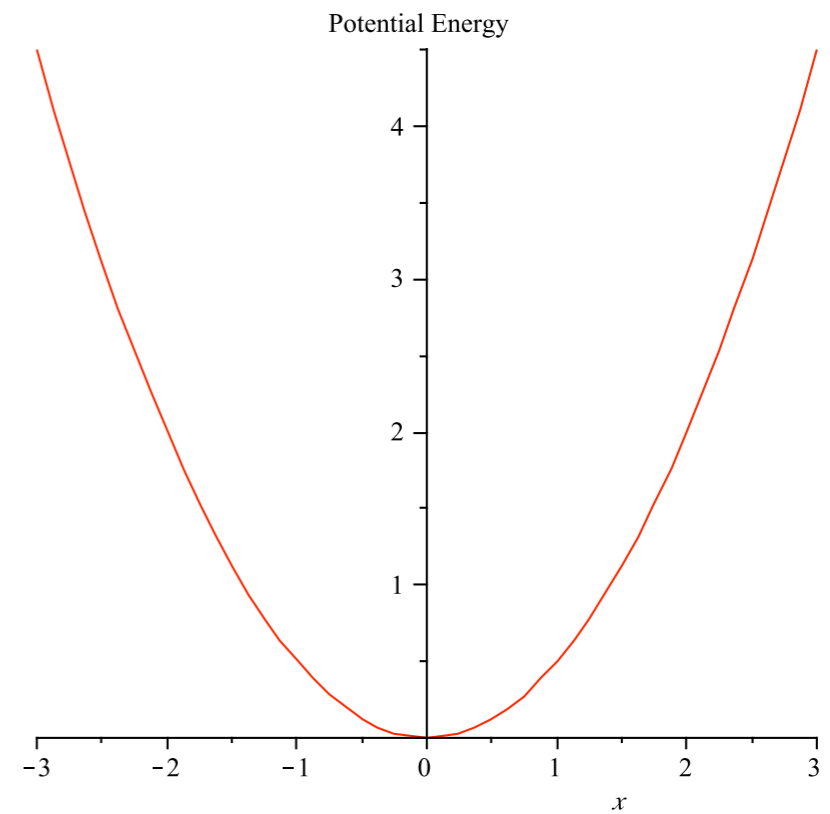
- Since:
$$N_{e-folds} = \int_{end}^{start} H dt \sim H_{inflc} \int_{end}^{start} dt = \frac{1}{3} (t_{end} - t_{start})$$

we can measure the time spent in the vicinity of the inflection point instead of the amount of e-foldings.

Damped Harmonic Oscillator

Damped Harmonic Oscillator

- A simpler example: a Harmonic Oscillator

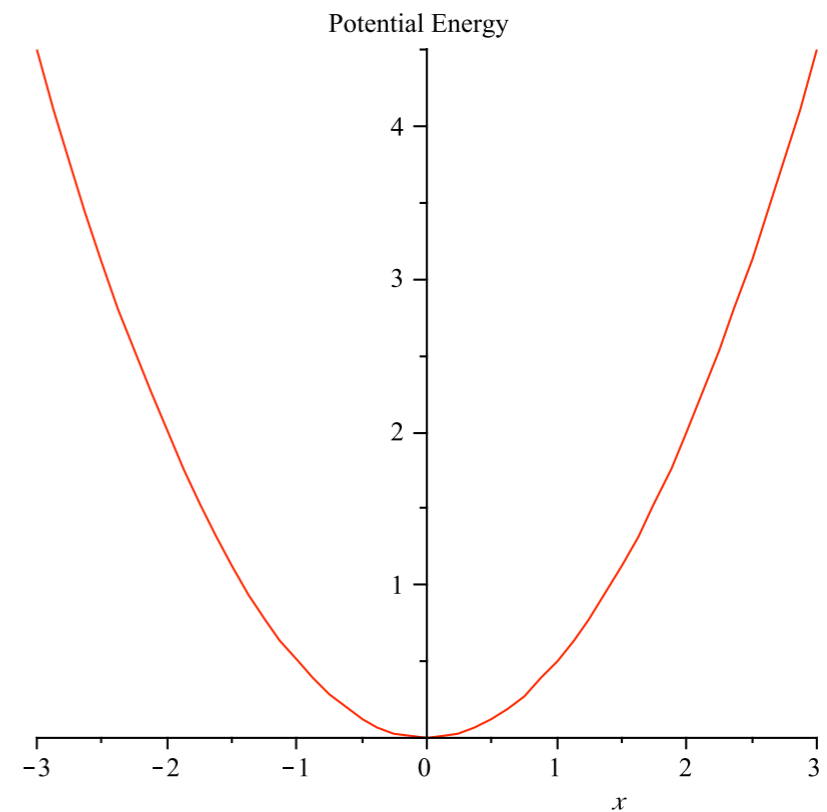


Damped Harmonic Oscillator

- A simpler example: a Harmonic Oscillator

For $V = \frac{1}{2}x^2$, we get the equation:

$$\ddot{x} + \gamma\dot{x} + x = 0$$



Damped Harmonic Oscillator

- A simpler example: a Harmonic Oscillator

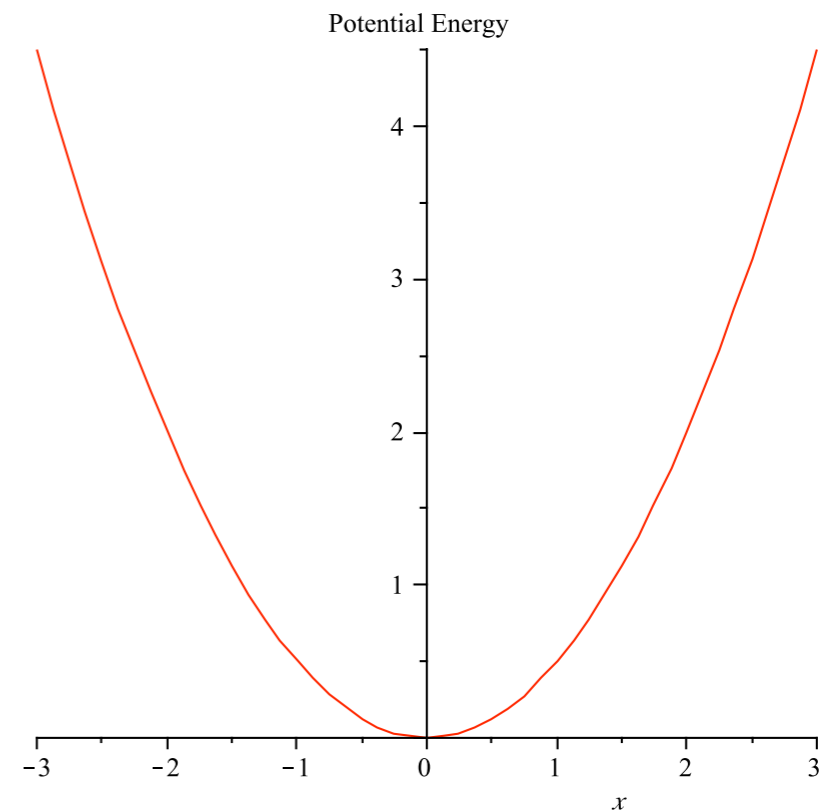
For $V = \frac{1}{2}x^2$, we get the equation:

$$\ddot{x} + \gamma\dot{x} + x = 0$$

Reducing to a system of 1st order equations:

$$y(t) = \dot{x}(t)$$

$$\dot{y}(t) = -ay(t) - x$$



Damped Harmonic Oscillator

- A simpler example: a Harmonic Oscillator

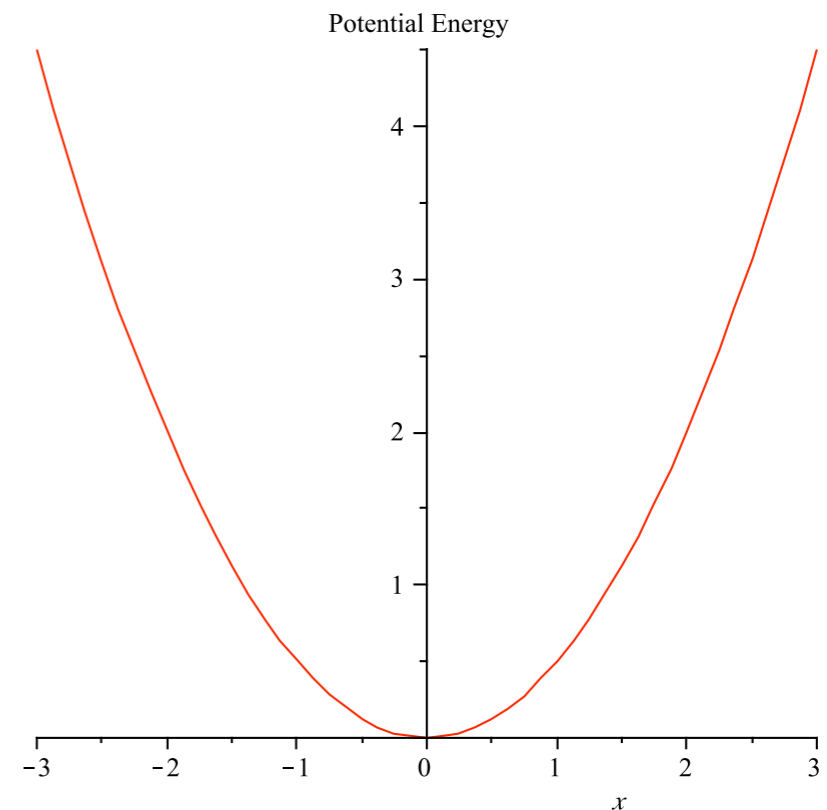
For $V = \frac{1}{2}x^2$, we get the equation:

$$\ddot{x} + \gamma\dot{x} + x = 0$$

Reducing to a system of 1st order equations:

$$y(t) = \dot{x}(t)$$

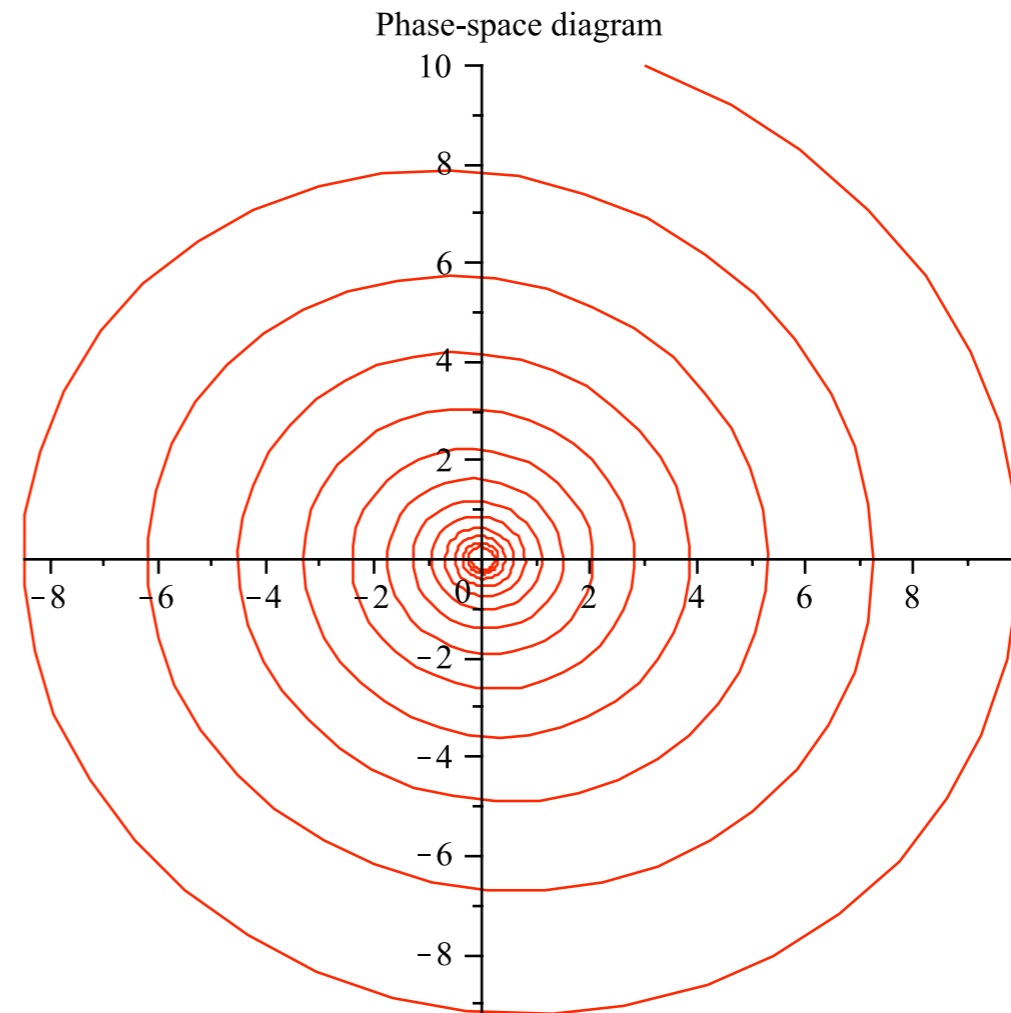
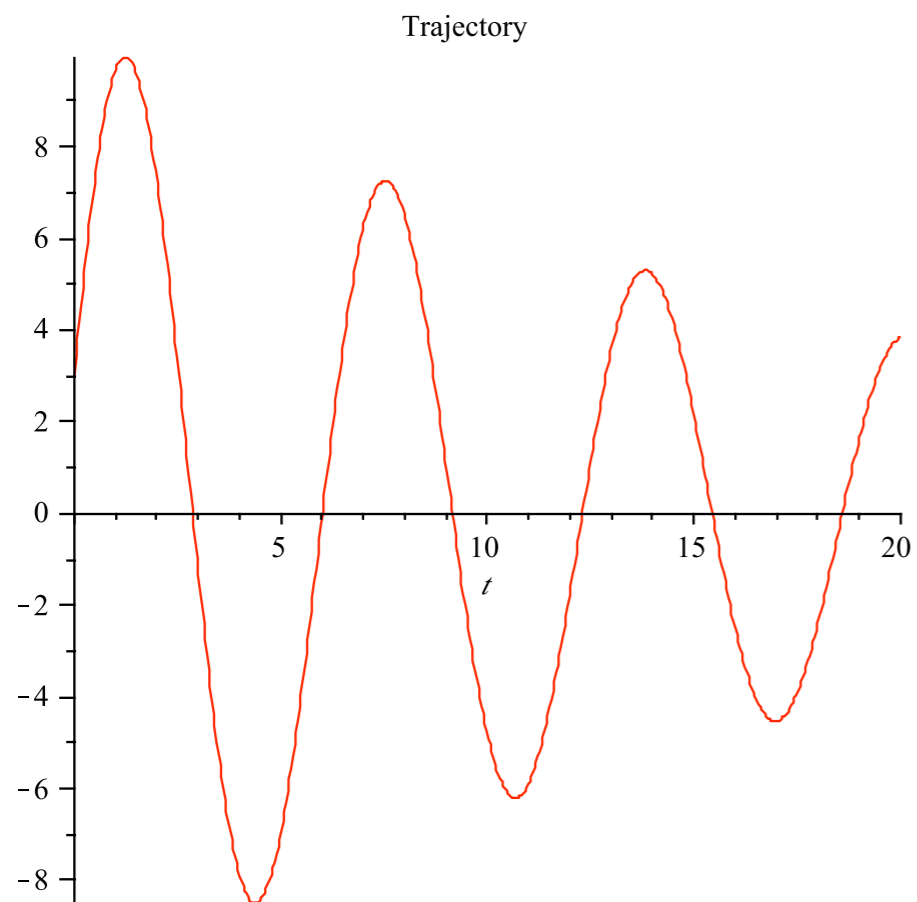
$$\dot{y}(t) = -ay(t) - x$$



We can proceed to draw the solutions in phase space.

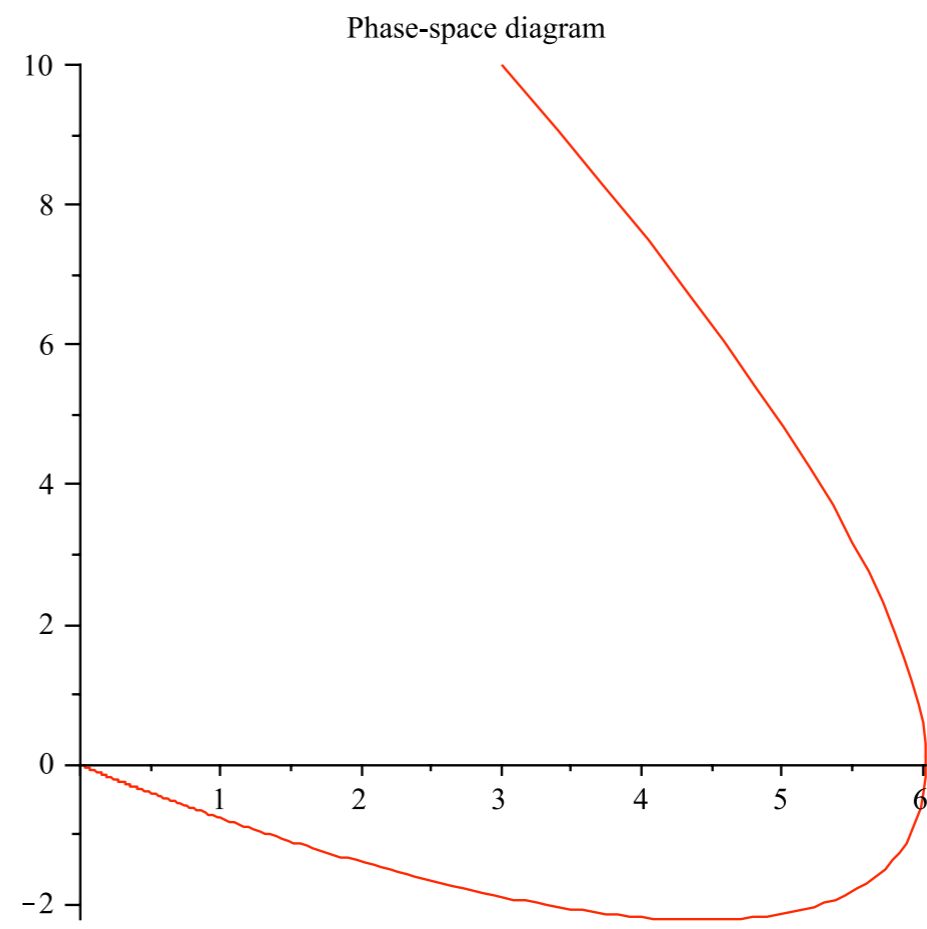
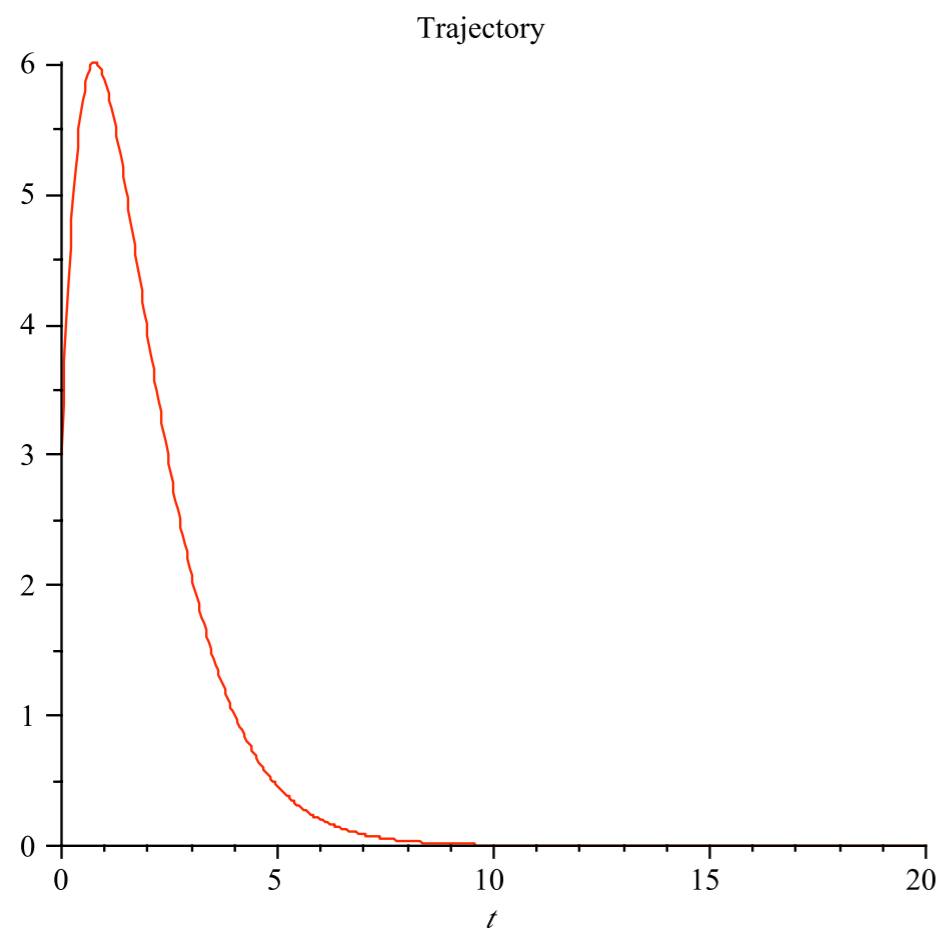
Harmonic Oscillator

- Left: trajectory for an arbitrary initial condition and $\gamma = 0.1$.
- Right: same trajectory in phase space.



Harmonic Oscillator

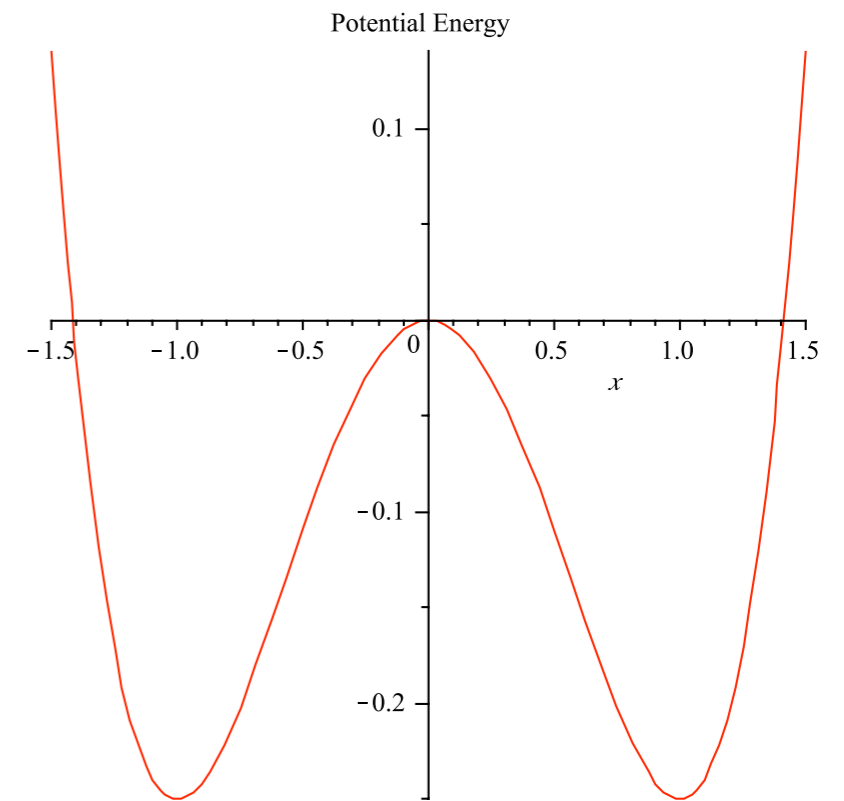
- Left: trajectory for an arbitrary initial condition and $\gamma = 2$. The motion decays before any oscillations occur. The point $x=0$ is asymptotically approached.
- Right: same trajectory in phase space.



Duffing Oscillator

Duffing Oscillator

- A slightly more complicated example:

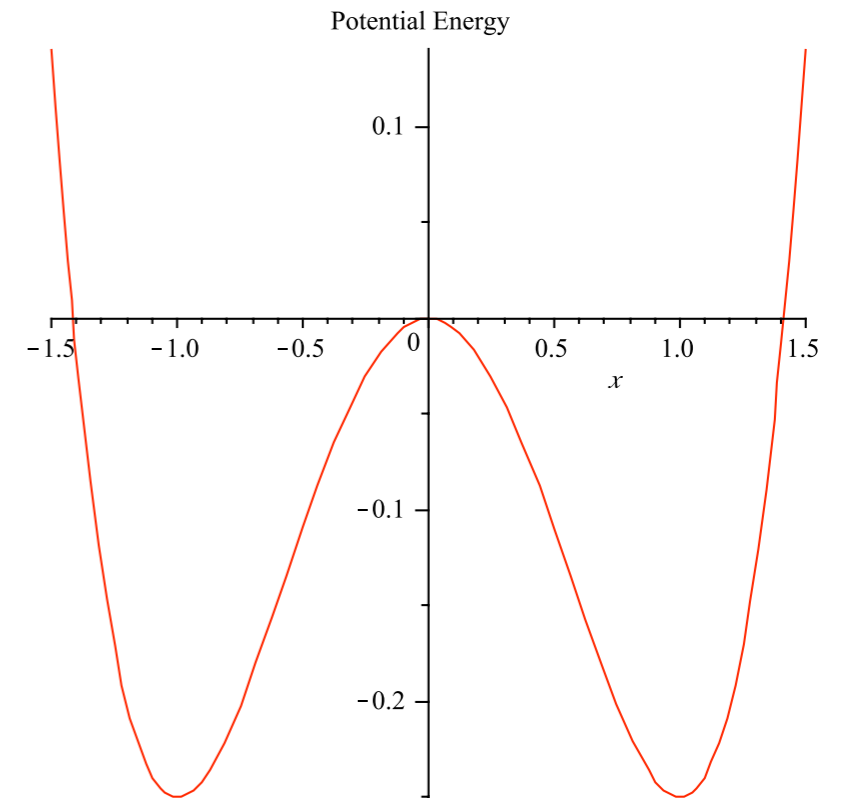


Duffing Oscillator

- A slightly more complicated example:

For $V = -\frac{1}{2}x^2 + \frac{1}{4}x^4$, we get the equation:

$$\ddot{x} + \gamma\dot{x} - x + x^3 = 0$$



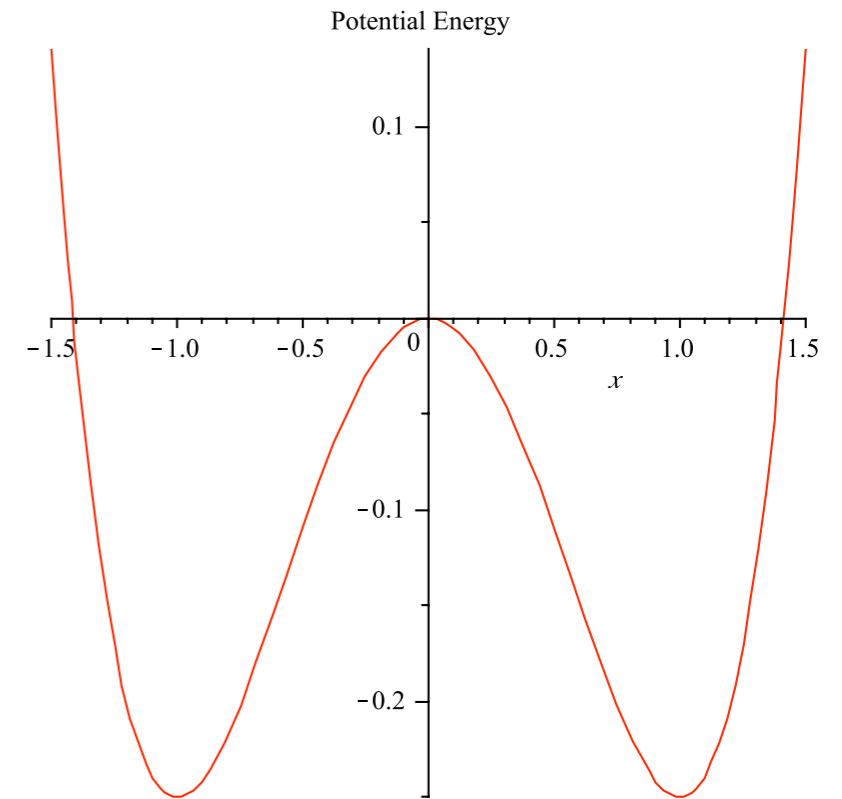
Duffing Oscillator

- A slightly more complicated example:

For $V = -\frac{1}{2}x^2 + \frac{1}{4}x^4$, we get the equation:

$$\ddot{x} + \gamma\dot{x} - x + x^3 = 0$$

This system has the following properties:



Duffing Oscillator

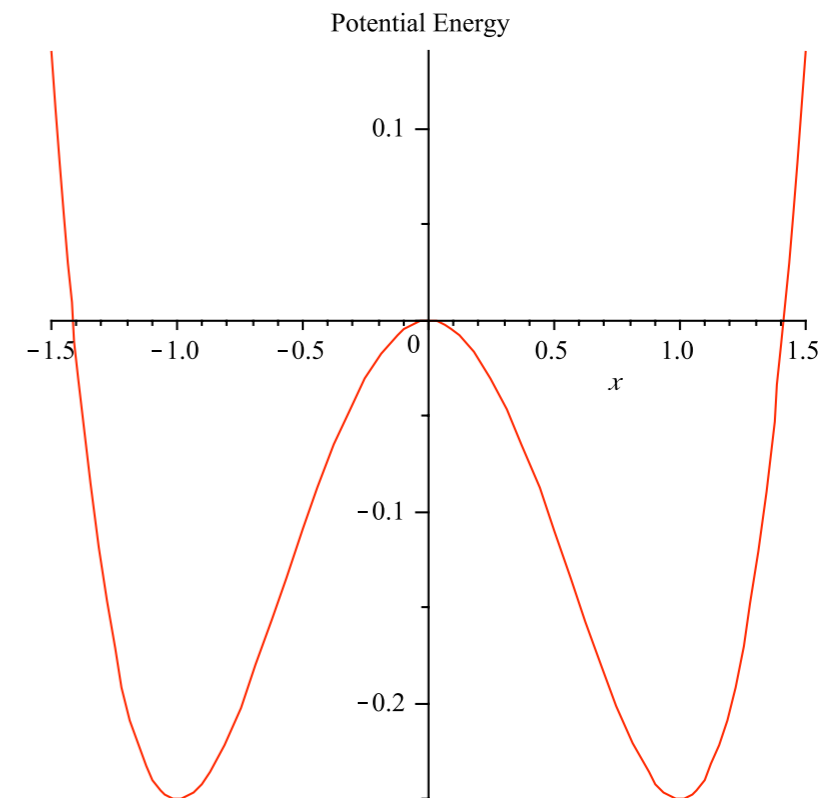
- A slightly more complicated example:

For $V = -\frac{1}{2}x^2 + \frac{1}{4}x^4$, we get the equation:

$$\ddot{x} + \gamma\dot{x} - x + x^3 = 0$$

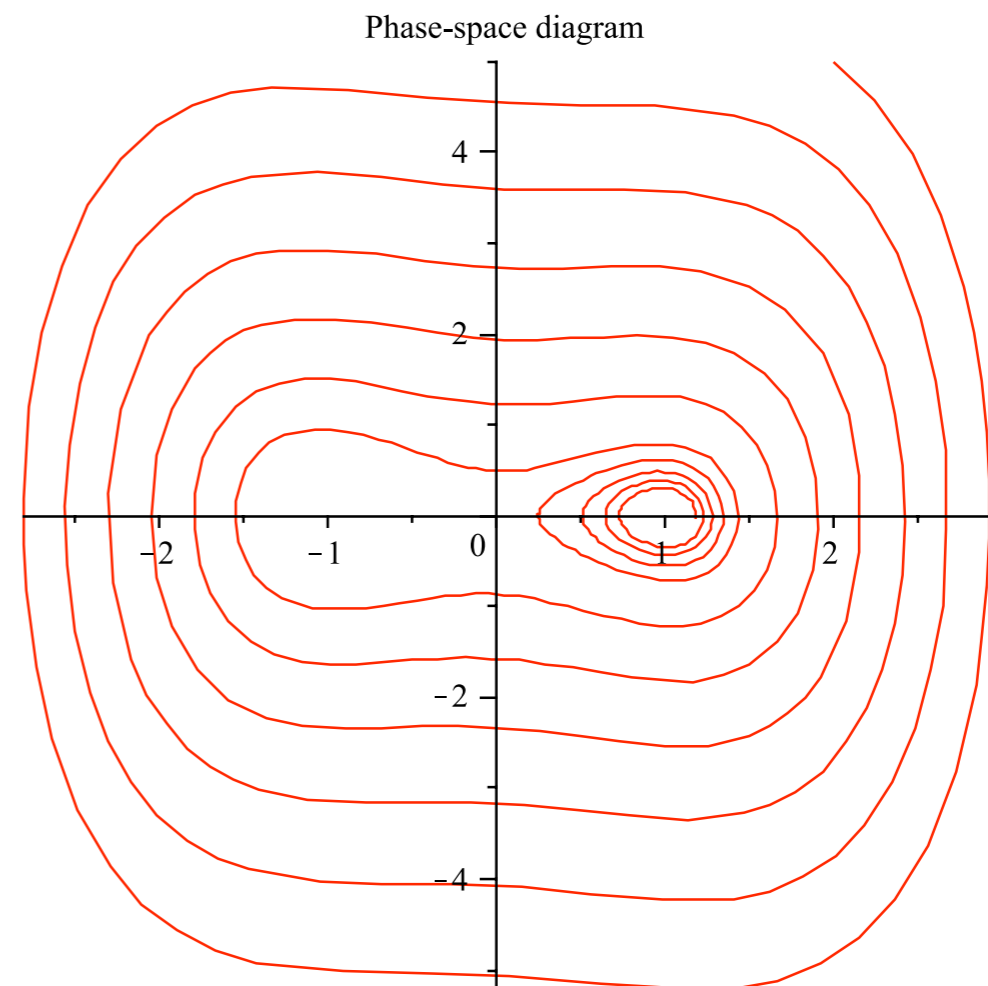
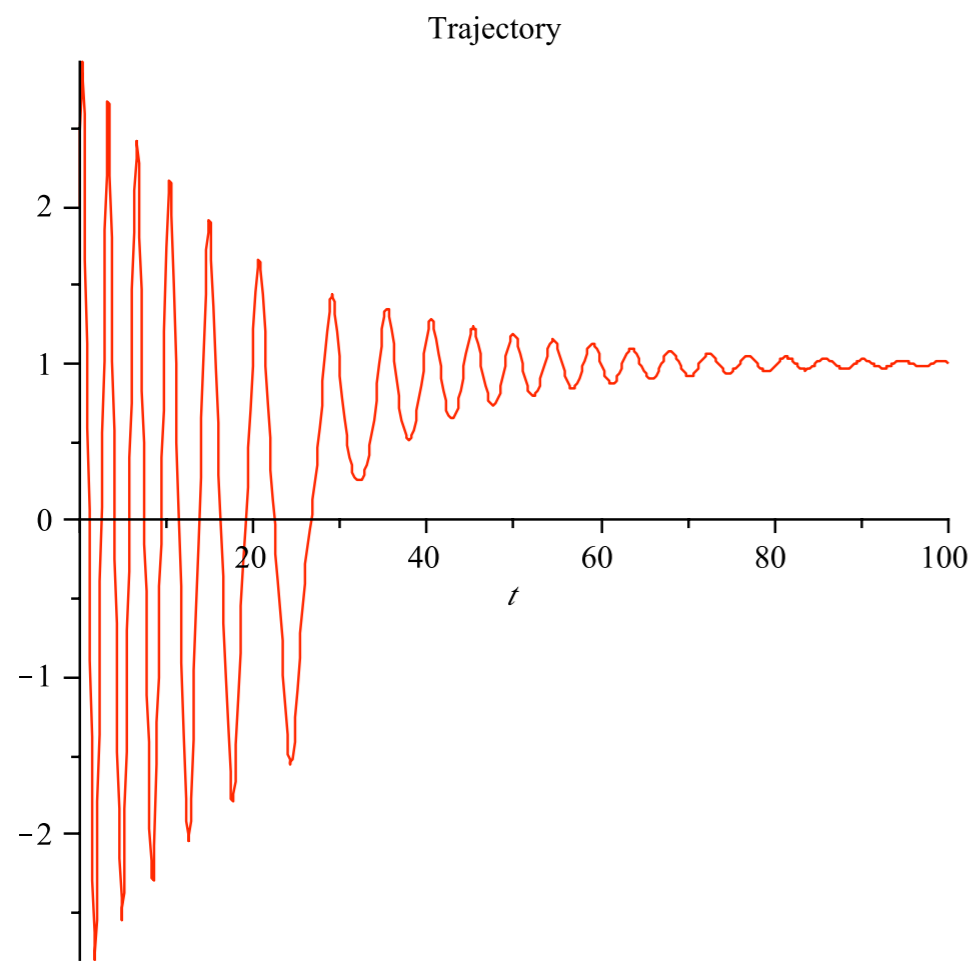
This system has the following properties:

- Potential has a double-well structure.
- $x = 0$ is an unstable equilibrium point.
- Particle motion ends in one of the wells.
- Unique phase-space trajectory per IC.
- Chaos appears as a result of the two wells connected by the unstable equilibrium point.



Duffing Oscillator

- Left: trajectory for arbitrary γ and initial condition. Particle falls into one well.
- Right: same trajectory in phase space. Trajectory converges to one side.

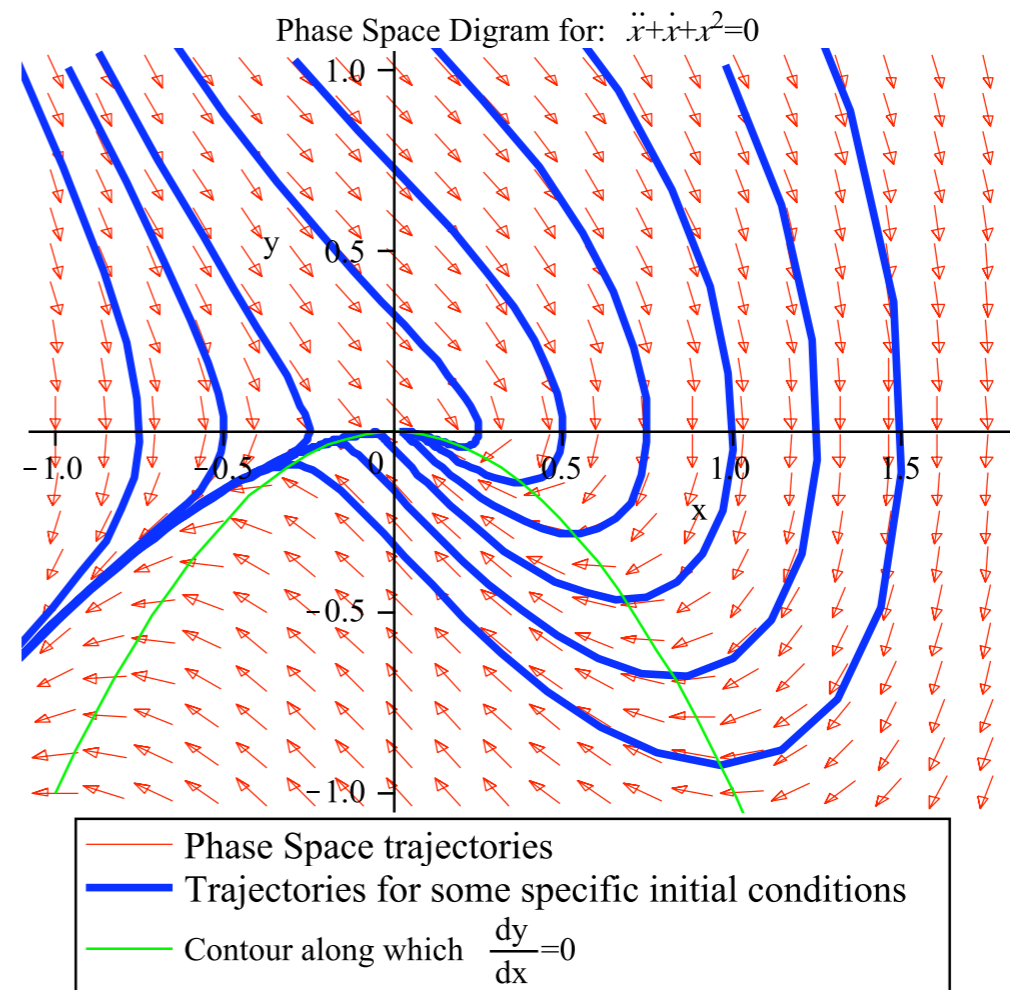


Phase Space Diagram

Phase Space Diagram

Reducing: $\ddot{x} + \dot{x} + x^2 = 0$ to:

$$\begin{aligned}\dot{x} &= y, \\ \dot{y} &= -y - x^2\end{aligned}$$



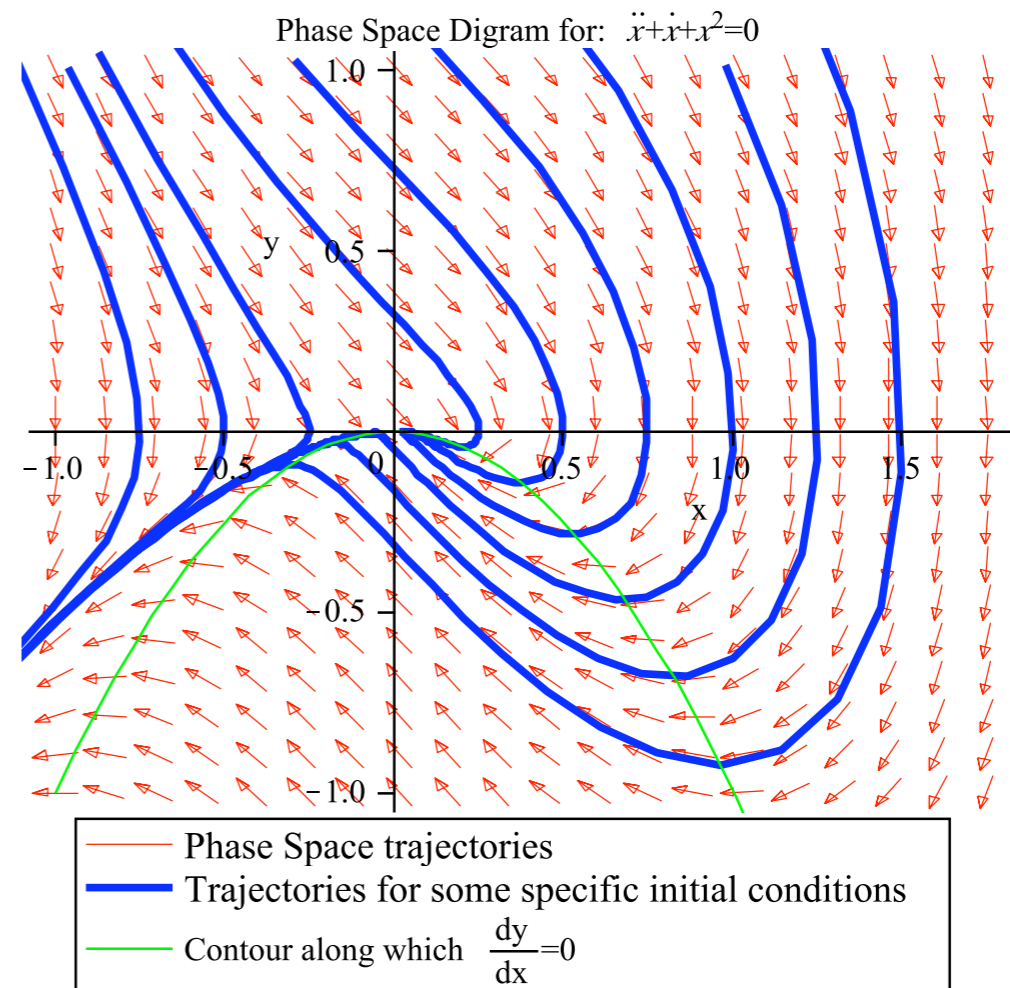
Phase Space Diagram

Reducing: $\ddot{x} + \dot{x} + x^2 = 0$ to:

$$\begin{aligned}\dot{x} &= y, \\ \dot{y} &= -y - x^2\end{aligned}$$

Examining the derivative:

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{-y - x^2}{y}$$



Phase Space Diagram

Reducing: $\ddot{x} + \dot{x} + x^2 = 0$ to:

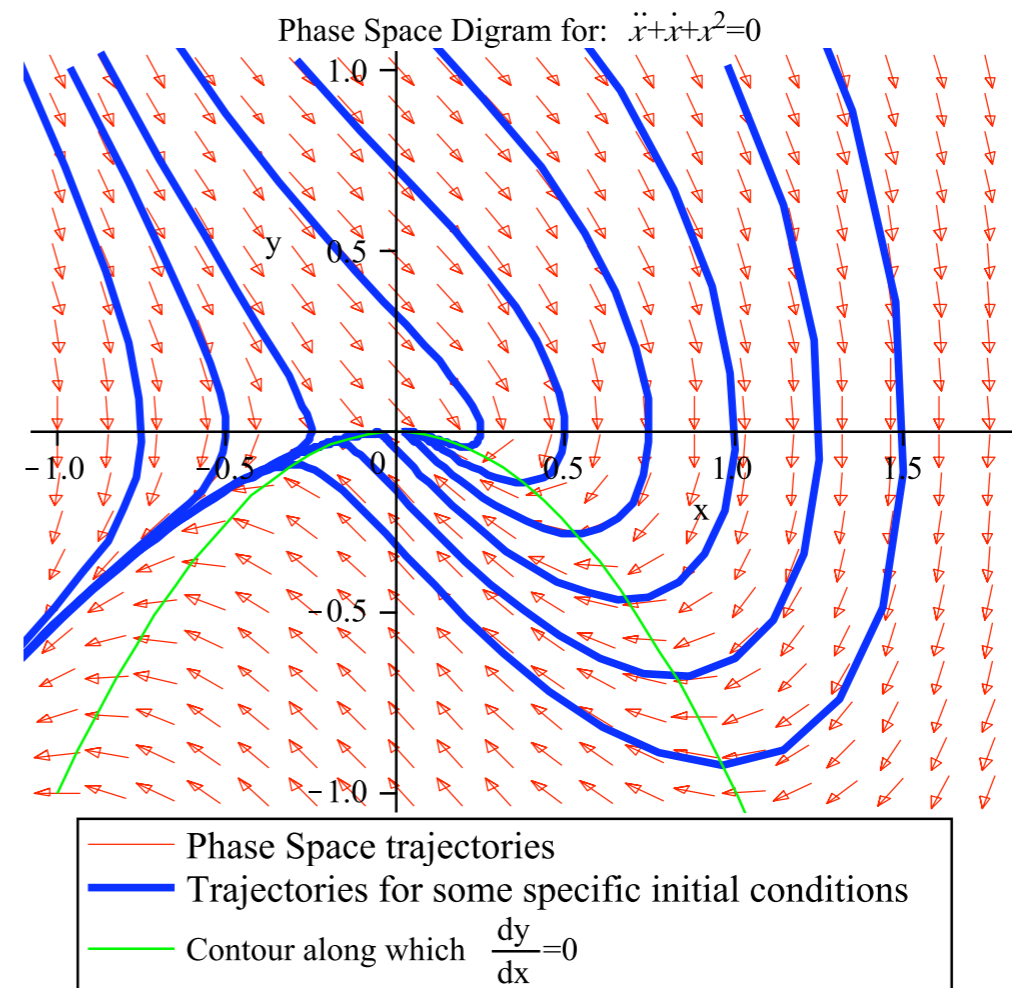
$$\begin{aligned}\dot{x} &= y, \\ \dot{y} &= -y - x^2\end{aligned}$$

Examining the derivative:

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{-y - x^2}{y}$$

we deduce:

- Crossing the x axis ($y=0$) the slope is always infinite.
- Crossing the y axis ($x=0$) the slope is always -1.
- Crossing the contour $y = -x^2$, the slope is always zero (for $x \neq 0$).
- For $y < 0$, outside (inside) the contour $y = -x^2$, the derivative is positive (negative) and the trajectories are monotonically increasing (decreasing).



Approximated Solutions

Approximated Solutions

The region near $x=0$ can be approached in two different ways:

$$\ddot{x} + \dot{x} + x^2 = 0$$

Approximated Solutions

The region near $x=0$ can be approached in two different ways:

$$\ddot{x} + \dot{x} + x^2 = 0$$

- We can neglect the x^2 term. Then the 2nd order equation becomes linear, with the solutions:

$$x = c_1 e^{-t} + c_2$$

Approximated Solutions

The region near $x=0$ can be approached in two different ways:

$$\ddot{x} + \dot{x} + x^2 = 0$$

- We can neglect the x^2 term. Then the 2nd order equation becomes linear, with the solutions:

$$x = c_1 e^{-t} + c_2$$

- We can also neglect the \ddot{x} term. Then the equation becomes 1st order, with the solutions:

$$x = \frac{1}{t + c}$$

Approximated Solutions

The region near $x=0$ can be approached in two different ways:

$$\ddot{x} + \dot{x} + x^2 = 0$$

- We can neglect the x^2 term. Then the 2nd order equation becomes linear, with the solutions:

$$x = c_1 e^{-t} + c_2$$

- We can also neglect the \ddot{x} term. Then the equation becomes 1st order, with the solutions:

$$x = \frac{1}{t + c}$$

- Solution (I) with $C_2 = 0$ approaches the origin from the right at $t \rightarrow \infty$. Solution (II) starts at the origin when $t \rightarrow -\infty$, coinciding with the curve along which the derivative dy/dx vanishes (the curve $y = -x^2$ with $x < 0$).

Approximated Solutions

The region near $x=0$ can be approached in two different ways:

$$\ddot{x} + \dot{x} + x^2 = 0$$

- We can neglect the x^2 term. Then the 2nd order equation becomes linear, with the solutions:

$$x = c_1 e^{-t} + c_2$$

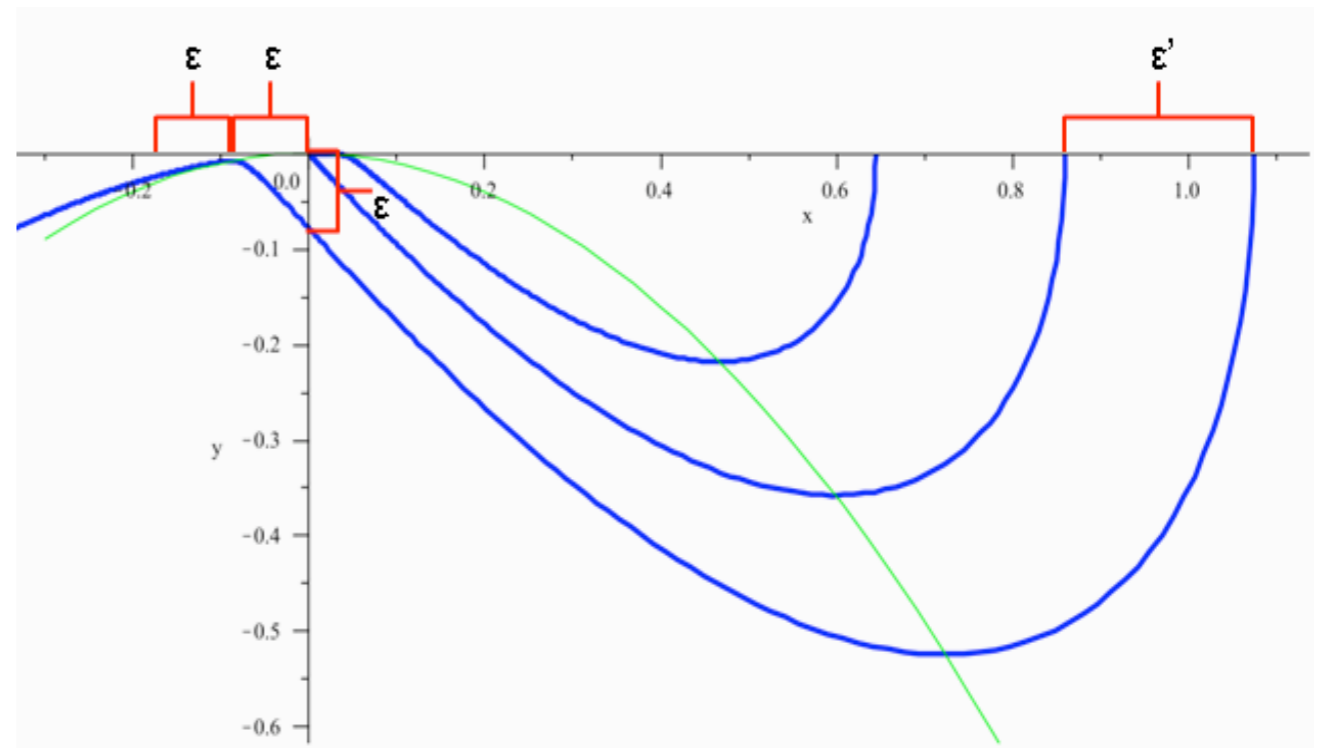
- We can also neglect the \ddot{x} term. Then the equation becomes 1st order, with the solutions:

$$x = \frac{1}{t + c}$$

- Solution (I) with $C_2 = 0$ approaches the origin from the right at $t \rightarrow \infty$. Solution (II) starts at the origin when $t \rightarrow -\infty$, coinciding with the curve along which the derivative dy/dx vanishes (the curve $y = -x^2$ with $x < 0$).
- Thus, to find the critical exponent we have to glue the two solutions.

Gluing the Solutions

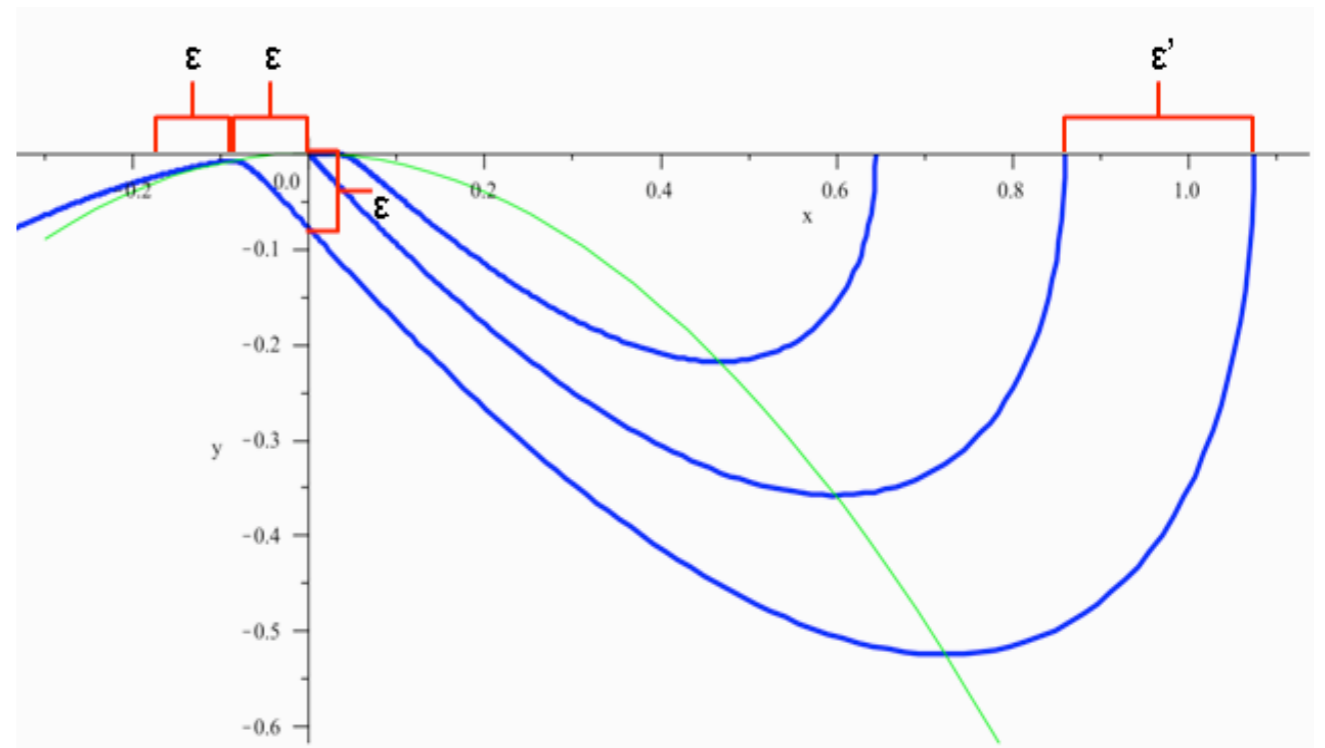
Gluing the Solutions



Gluing the Solutions

- We start with approximation (I):

$$x = ce^{-t} - \epsilon \quad , \quad y = -ce^{-t}$$

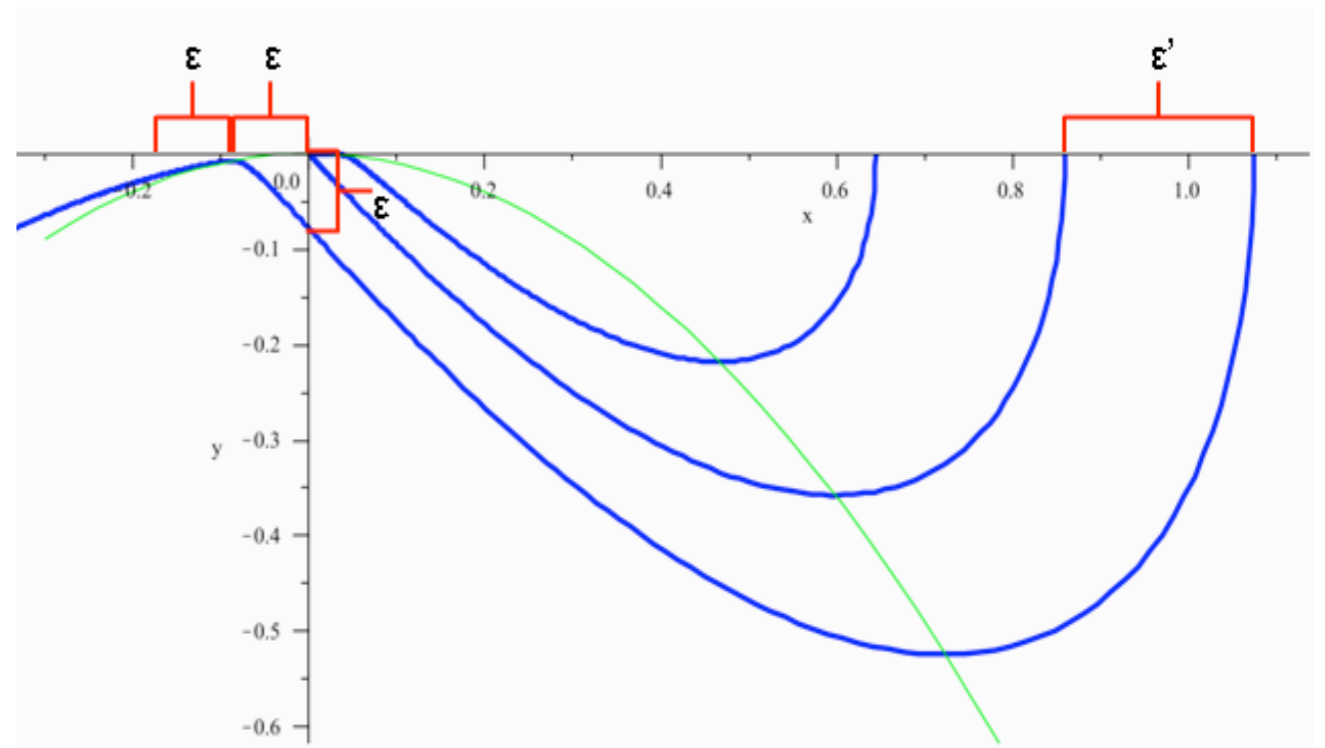


Gluing the Solutions

- We start with approximation (I):

$$x = ce^{-t} - \epsilon \quad , \quad y = -ce^{-t}$$

- This approximation breaks down when $\dot{x} \sim x^2 \sim \epsilon^2$, which happens at:



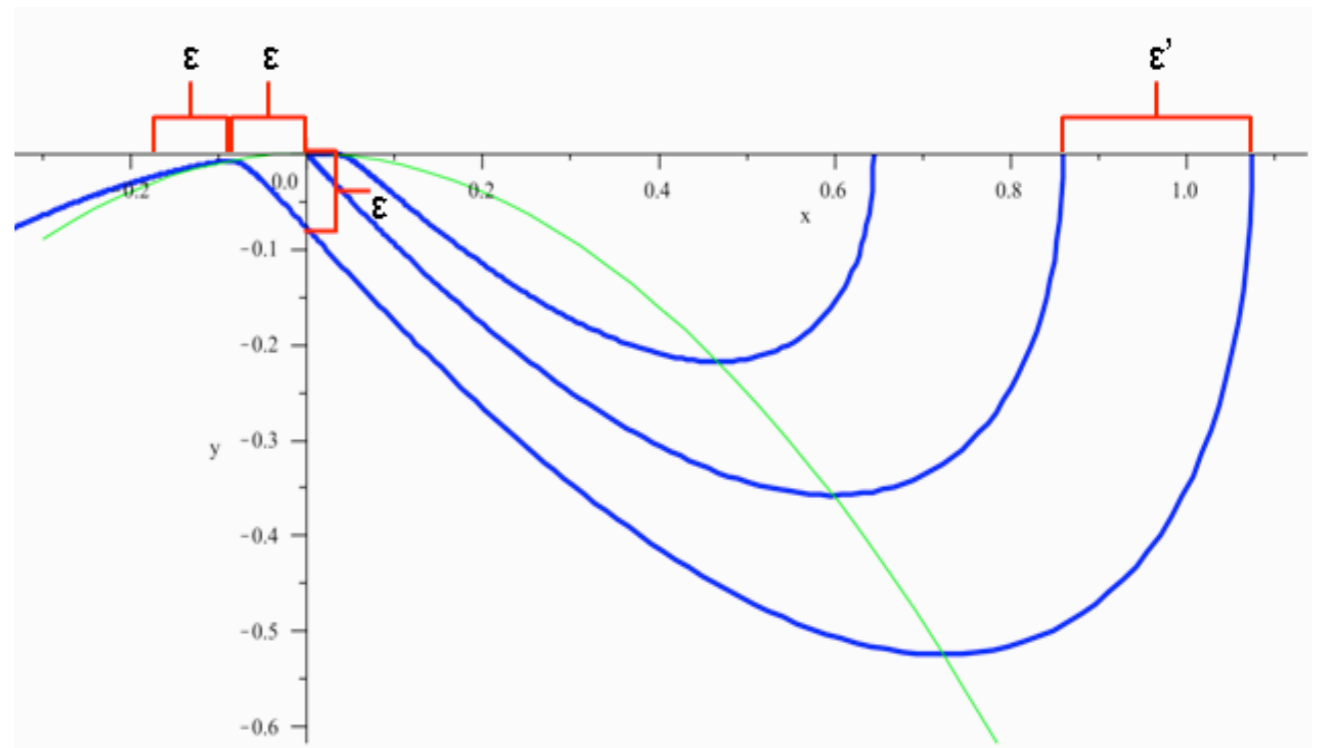
Gluing the Solutions

- We start with approximation (I):

$$x = ce^{-t} - \epsilon \quad , \quad y = -ce^{-t}$$

- This approximation breaks down when $\dot{x} \sim x^2 \sim \epsilon^2$, which happens at:

$$\dot{x}_* \simeq -\epsilon^2 \quad , \quad x_* \simeq \epsilon^2 - \epsilon \sim -\epsilon \quad , \quad t_* \simeq \log(c/\epsilon^2)$$



Gluing the Solutions

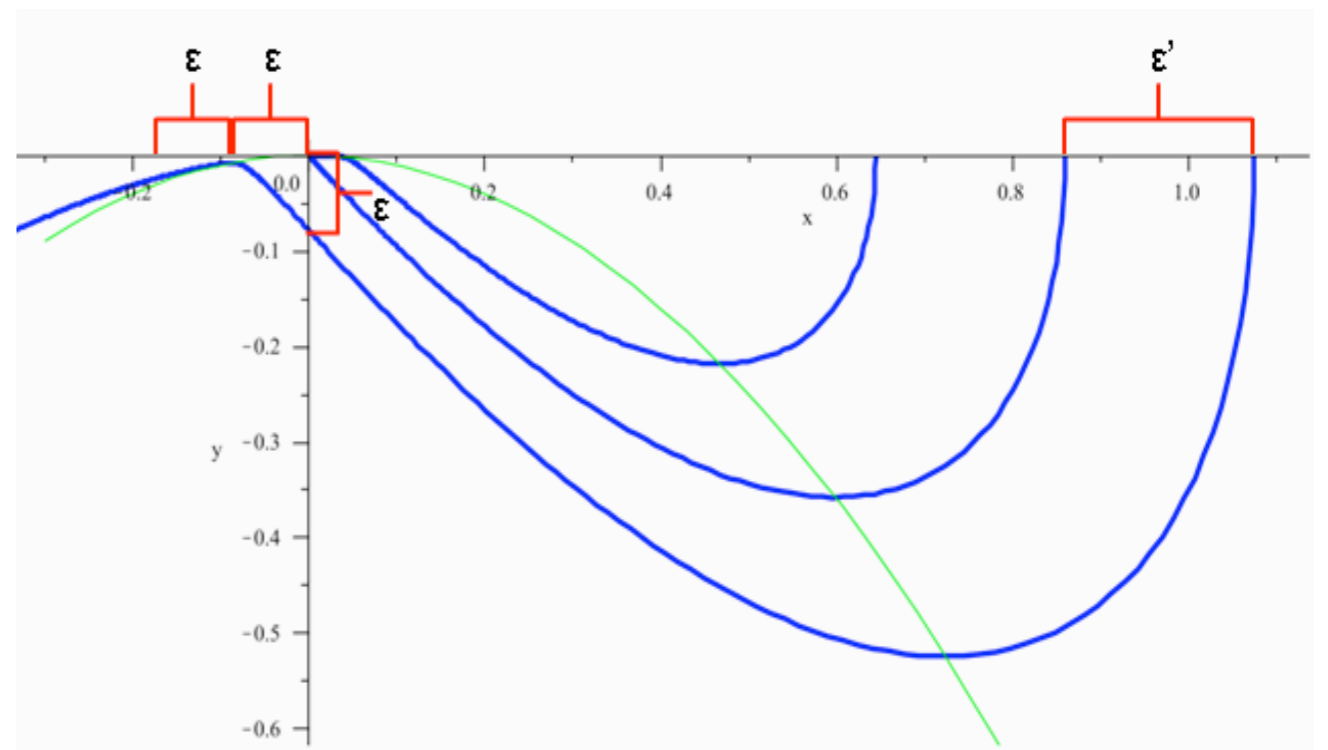
- We start with approximation (I):

$$x = ce^{-t} - \epsilon \quad , \quad y = -ce^{-t}$$

- This approximation breaks down when $\dot{x} \sim x^2 \sim \epsilon^2$, which happens at:

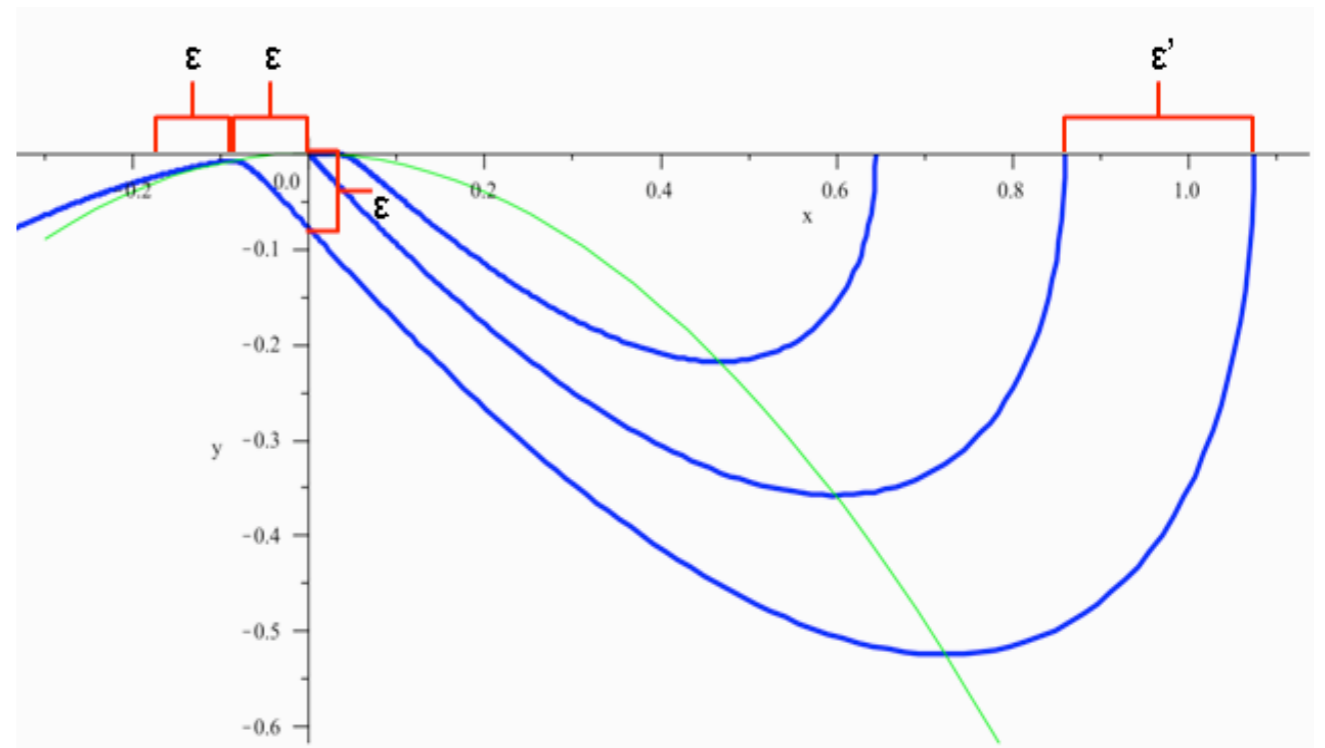
$$\dot{x}_* \simeq -\epsilon^2 \quad , \quad x_* \simeq \epsilon^2 - \epsilon \sim -\epsilon \quad , \quad t_* \simeq \log(c/\epsilon^2)$$

- Thus the first approximation is satisfactory up to $x \sim -\epsilon$, which, is in the vicinity of the curve along which approximation (II) is valid. However, as we saw above, the solution trajectory crosses this curve parallel to the y axis and therefore must deviate from it.



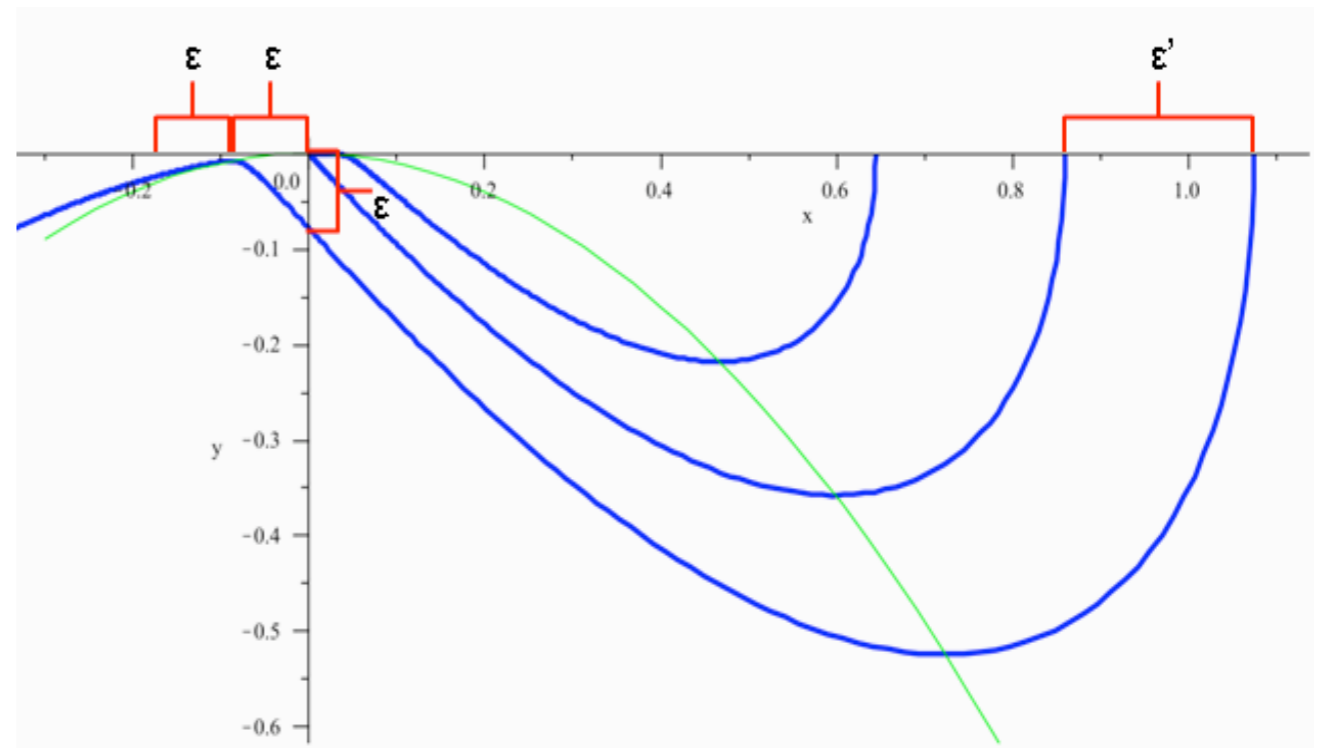
Gluing the Solutions

Gluing the Solutions



Gluing the Solutions

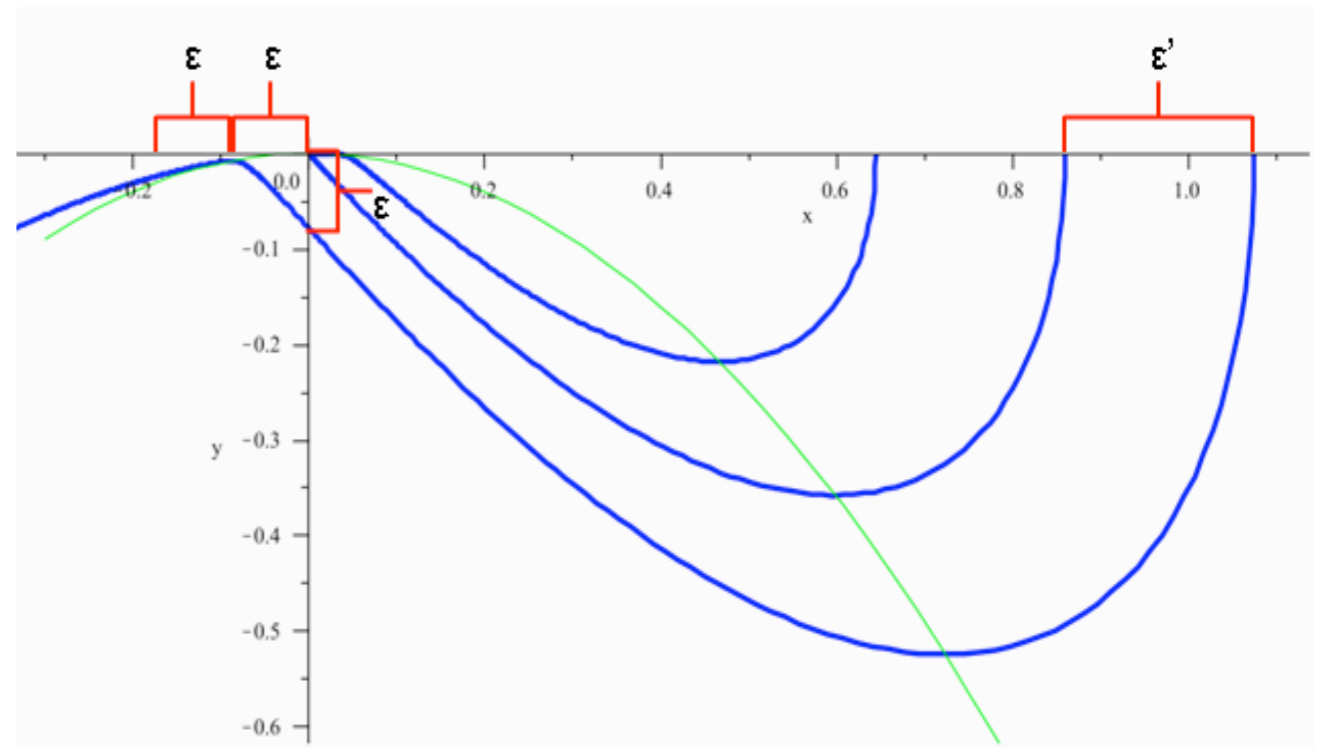
- To find the deviation, we start from:



Gluing the Solutions

- To find the deviation, we start from:

$$x \sim -\epsilon - \delta x \quad , \quad \dot{x} \sim -\epsilon^2$$

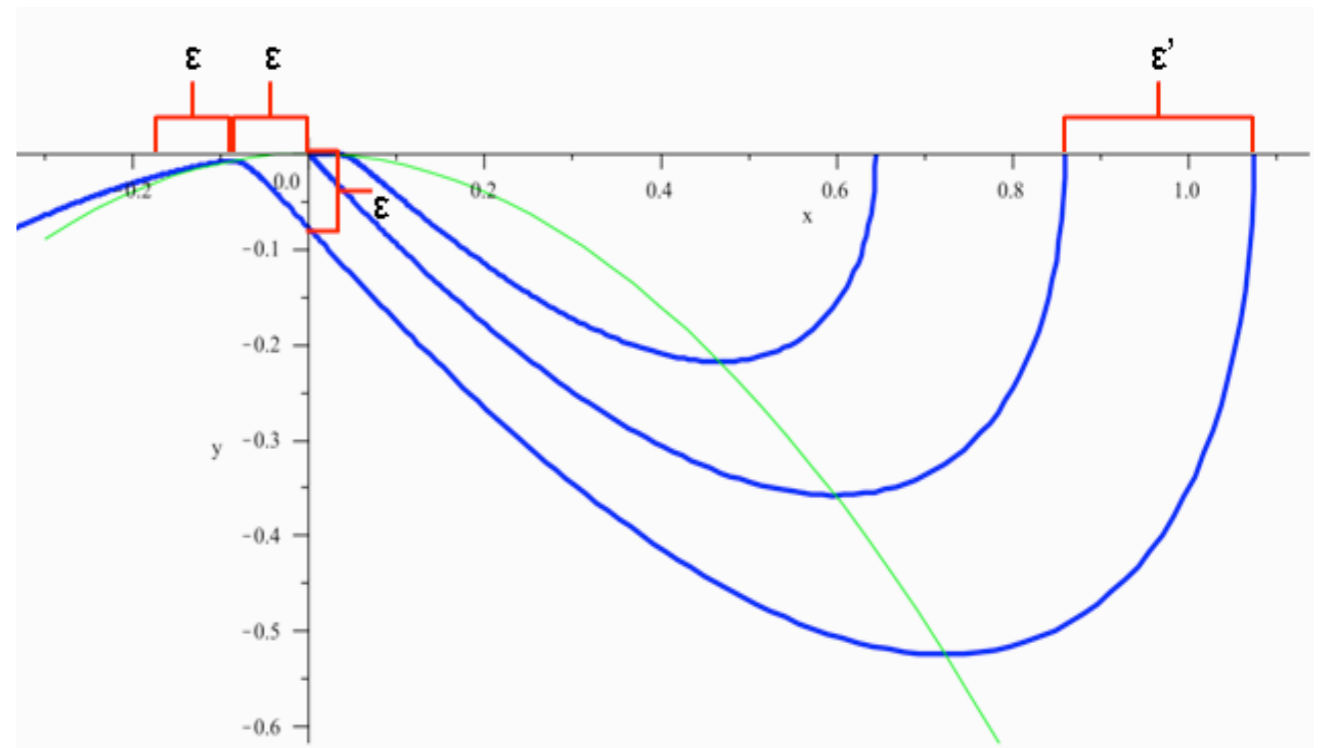


Gluing the Solutions

- To find the deviation, we start from:

$$x \sim -\epsilon - \delta x \quad , \quad \dot{x} \sim -\epsilon^2$$

and stop when $\ddot{x} \sim \dot{x} \sim \epsilon^2$. We find that:



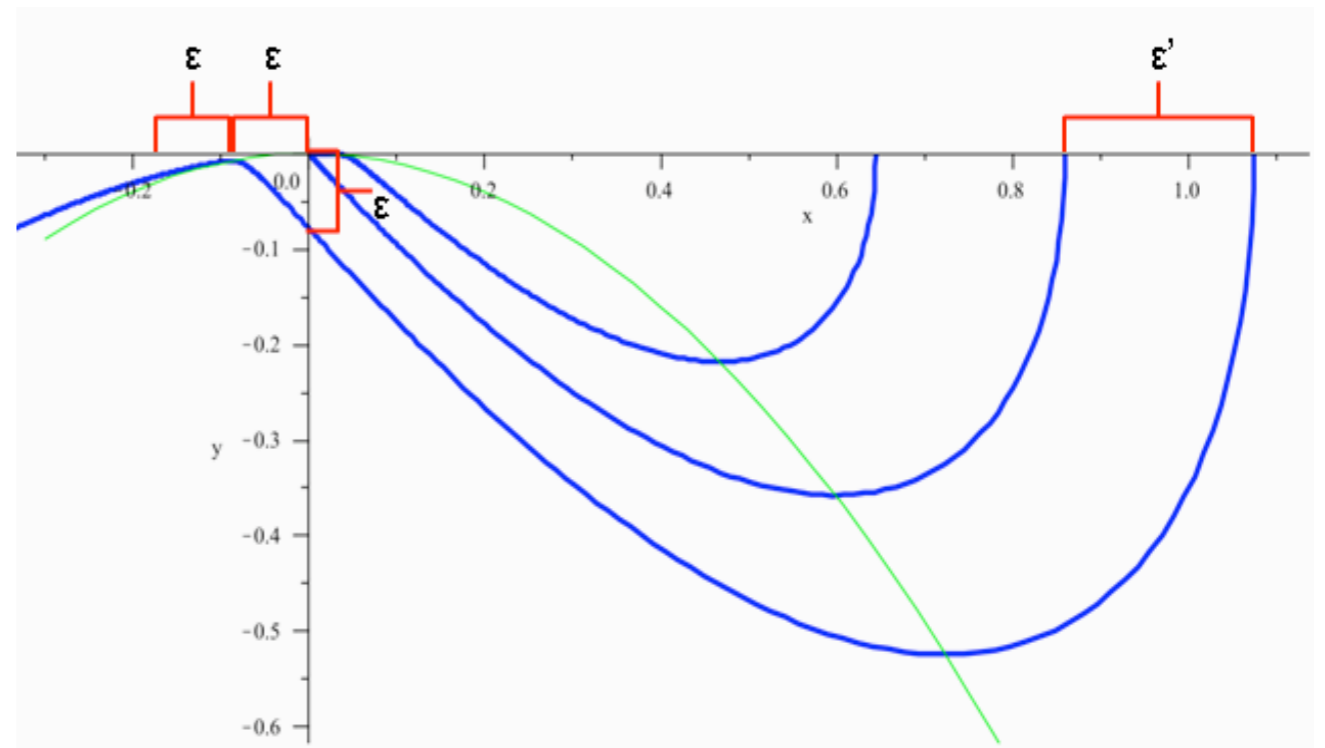
Gluing the Solutions

- To find the deviation, we start from:

$$x \sim -\epsilon - \delta x \quad , \quad \dot{x} \sim -\epsilon^2$$

and stop when $\ddot{x} \sim \dot{x} \sim \epsilon^2$. We find that:

$$\begin{aligned} \ddot{x} &= \dot{y} = \frac{dy}{dx} \frac{dx}{dt} = \frac{-y - x^2}{y} y = -y - x^2 \\ &= \cancel{\epsilon^2} - \cancel{\epsilon^2} - 2\delta x \epsilon - (\delta x)^2 \sim \delta x \epsilon \end{aligned}$$



Gluing the Solutions

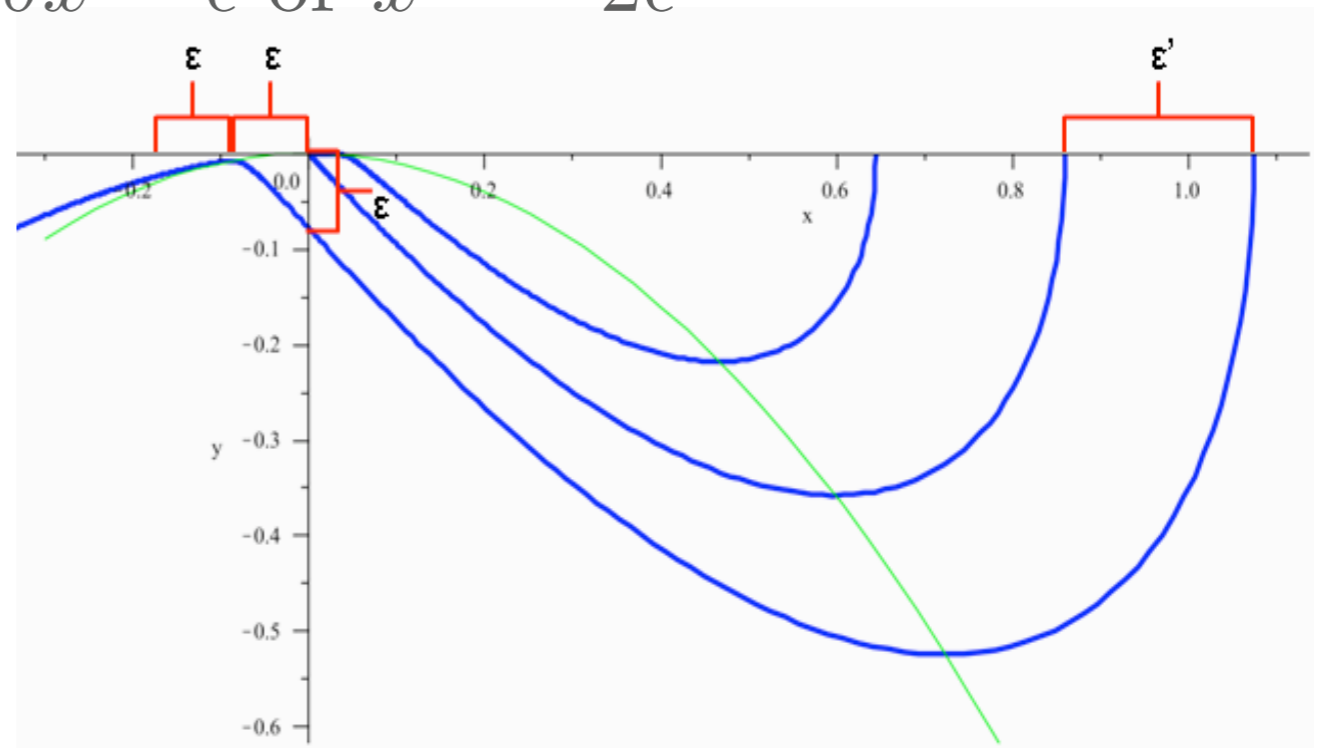
- To find the deviation, we start from:

$$x \sim -\epsilon - \delta x \quad , \quad \dot{x} \sim -\epsilon^2$$

and stop when $\ddot{x} \sim \dot{x} \sim \epsilon^2$. We find that:

$$\begin{aligned} \ddot{x} &= \dot{y} = \frac{dy}{dx} \frac{dx}{dt} = \frac{-y - x^2}{y} y = -y - x^2 \\ &= \epsilon^2 - \epsilon^2 - 2\delta x \epsilon - (\delta x)^2 \sim \delta x \epsilon \end{aligned}$$

which is no longer negligible once: $\delta x \sim \epsilon$ or $x \sim -2\epsilon$



Gluing the Solutions

- To find the deviation, we start from:

$$x \sim -\epsilon - \delta x \quad , \quad \dot{x} \sim -\epsilon^2$$

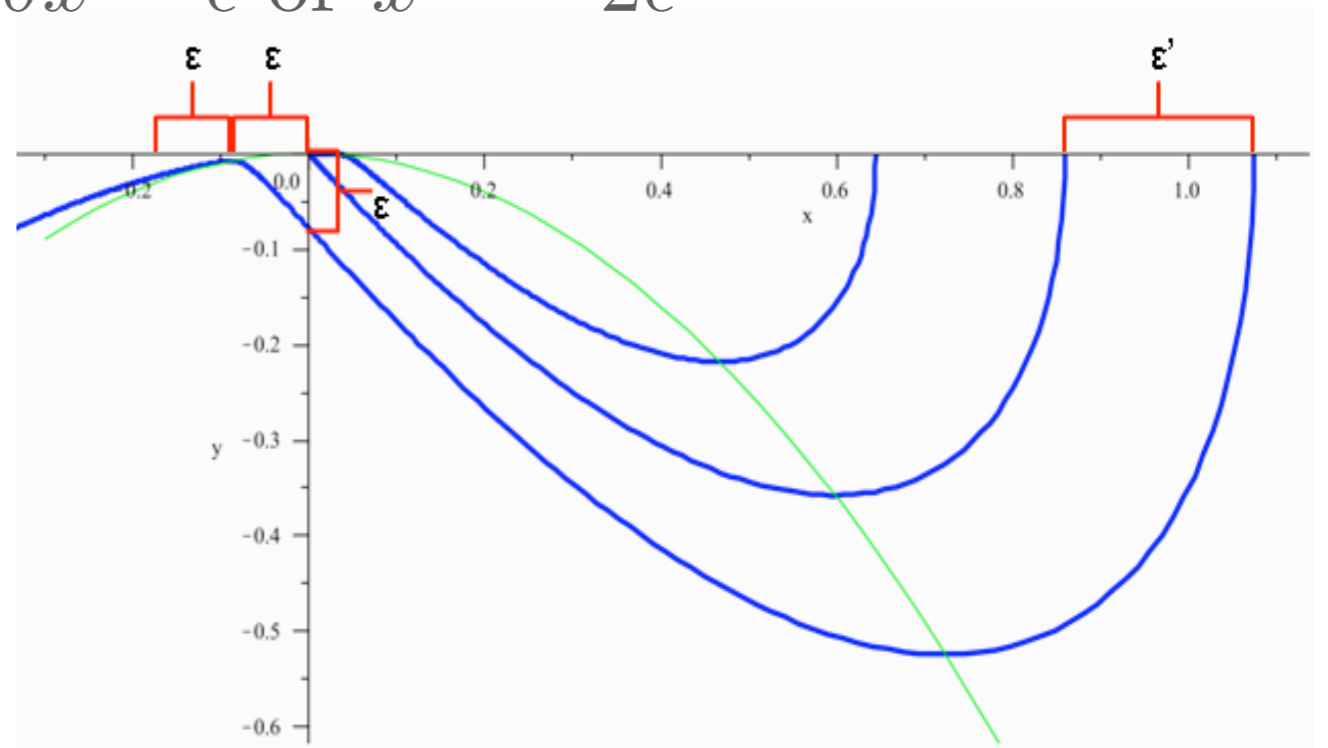
and stop when $\ddot{x} \sim \dot{x} \sim \epsilon^2$. We find that:

$$\begin{aligned} \ddot{x} &= \dot{y} = \frac{dy}{dx} \frac{dx}{dt} = \frac{-y - x^2}{y} y = -y - x^2 \\ &= \cancel{\epsilon^2} - \cancel{\epsilon^2} - 2\delta x \epsilon - (\delta x)^2 \sim \delta x \epsilon \end{aligned}$$

which is no longer negligible once: $\delta x \sim \epsilon$ or $x \sim -2\epsilon$

- The remaining missing link is the relation between ϵ' and ϵ . Since the equations are regular in this region the relation between them is linear:

$$\epsilon' \propto \epsilon$$



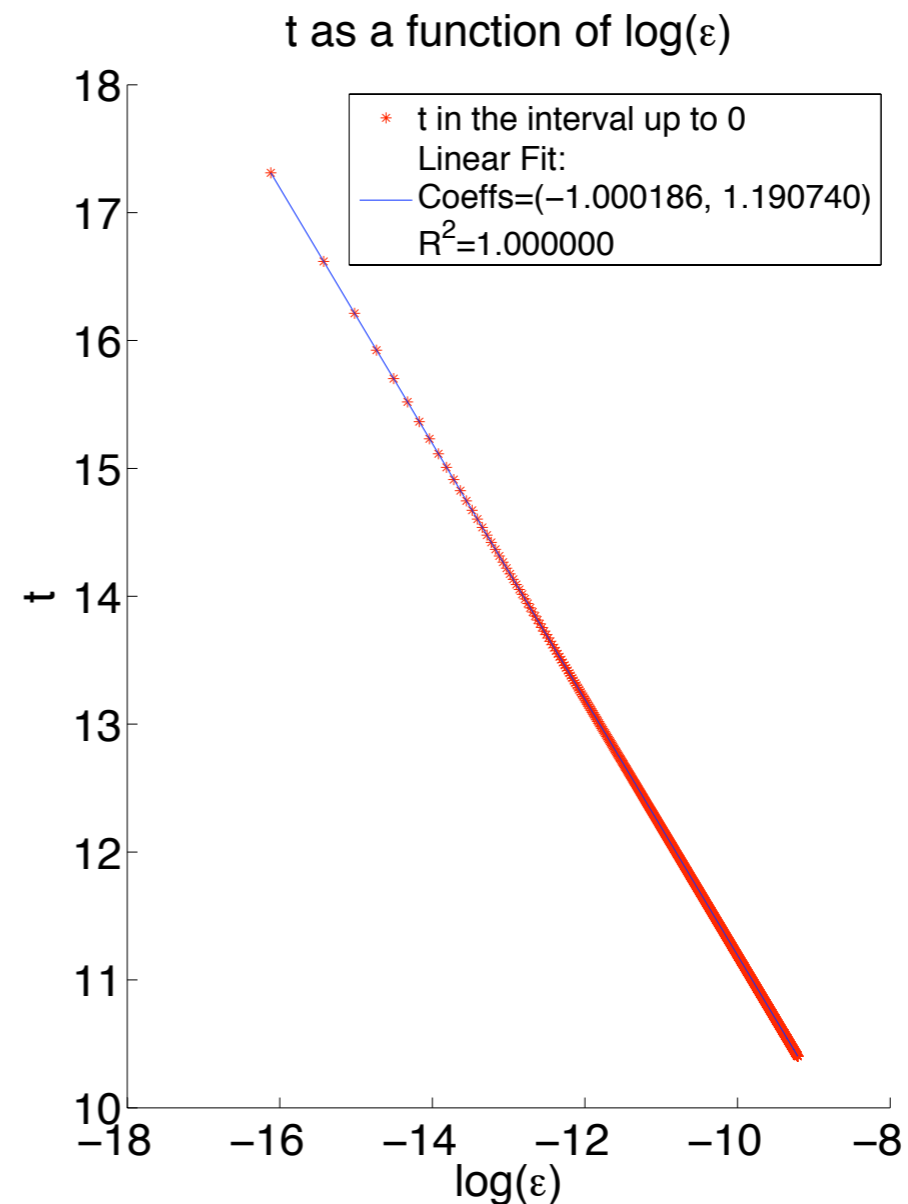
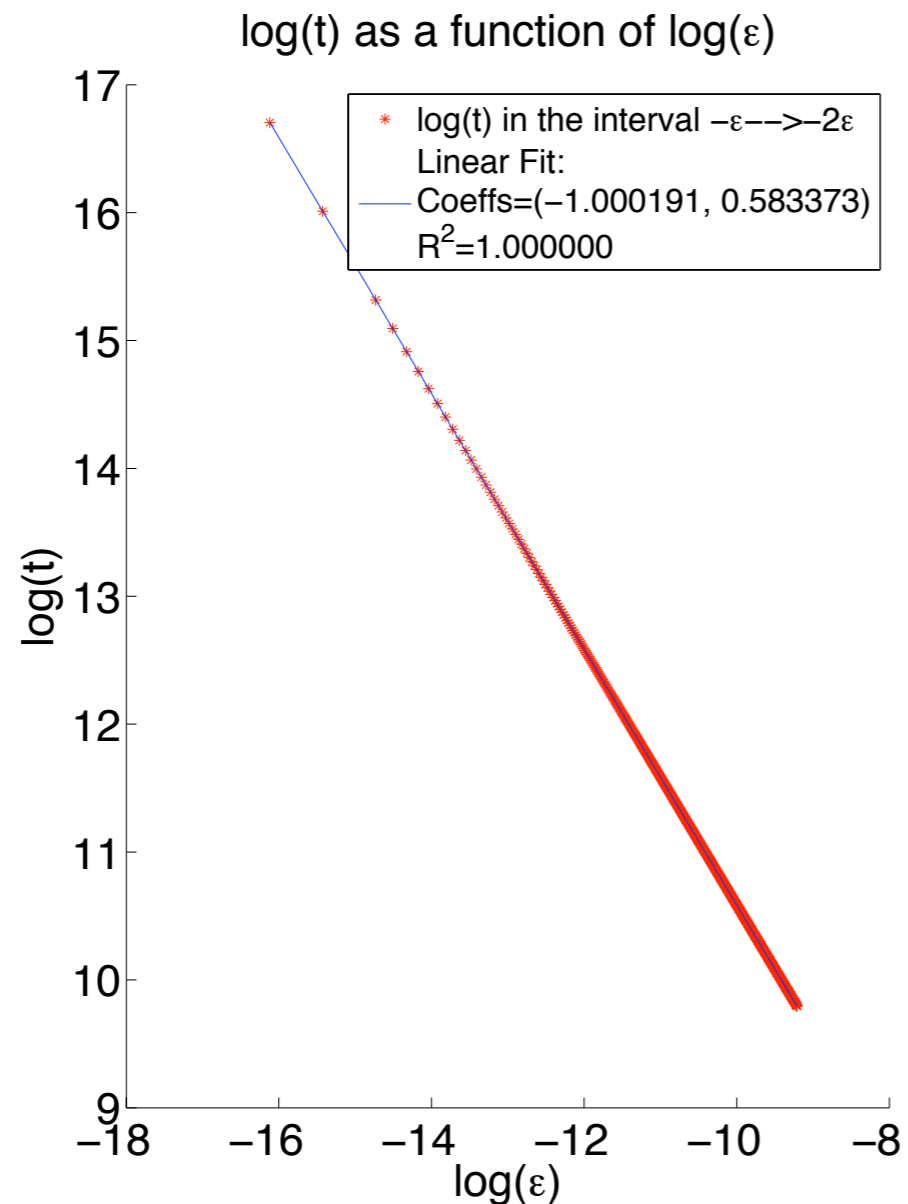
Proof for Critical Exponents

Proof for Critical Exponents

- We conclude that the time spent by the inflaton in the interval to the right of $x=0$ goes like $t_{right} \sim -\log \epsilon$, while the majority of the time is spent in the interval $[-2\epsilon, -\epsilon]$, and satisfies: $t_{left} \sim \epsilon^{-1}$.

Proof for Critical Exponents

- We conclude that the time spent by the inflaton in the interval to the right of $x=0$ goes like $t_{right} \sim -\log \epsilon$, while the majority of the time is spent in the interval $[-2\epsilon, -\epsilon]$, and satisfies: $t_{left} \sim \epsilon^{-1}$.



Higher Order Terms and Exponents

Higher Order Terms and Exponents

What about the higher order cases mentioned above?

Higher Order Terms and Exponents

What about the higher order cases mentioned above?

- With the same considerations, for $\ddot{x} + \dot{x} + x^{2n} = 0$ we get: $x \sim \frac{1}{t^{2n-1}}$

Higher Order Terms and Exponents

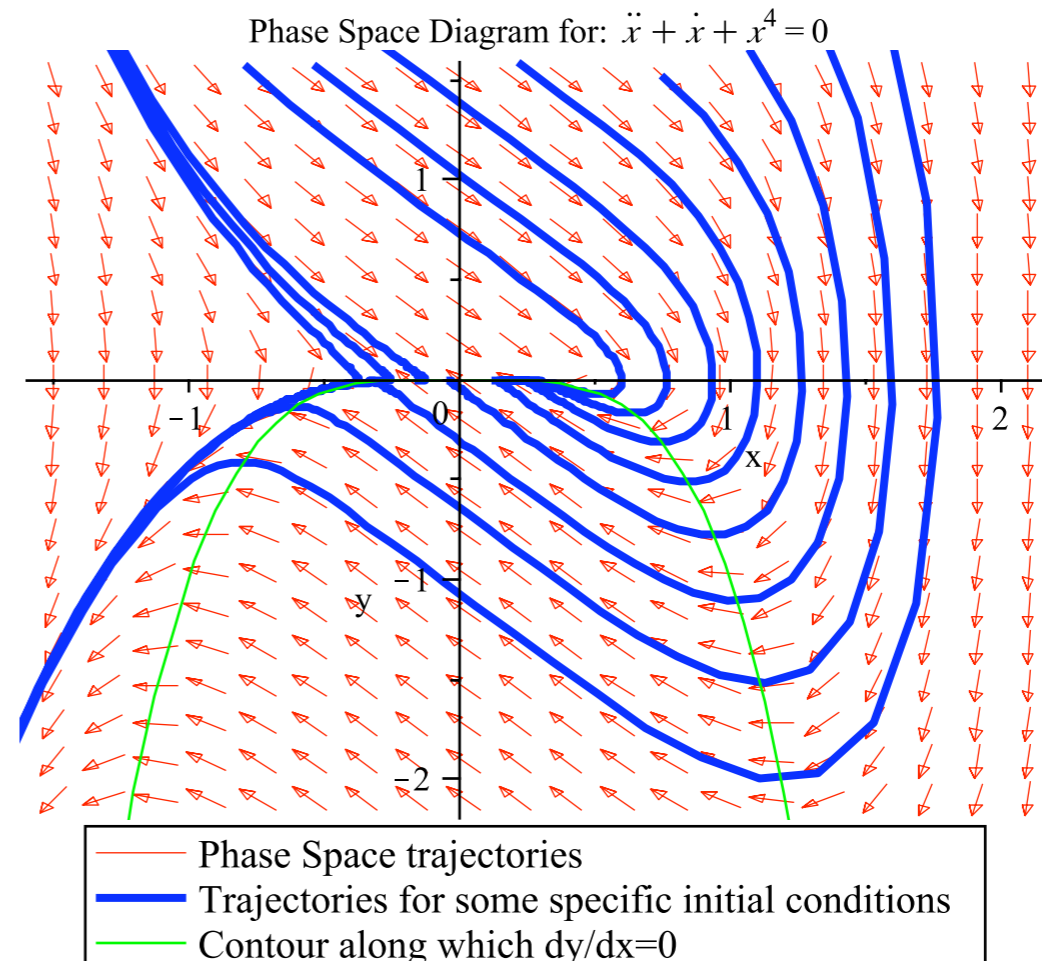
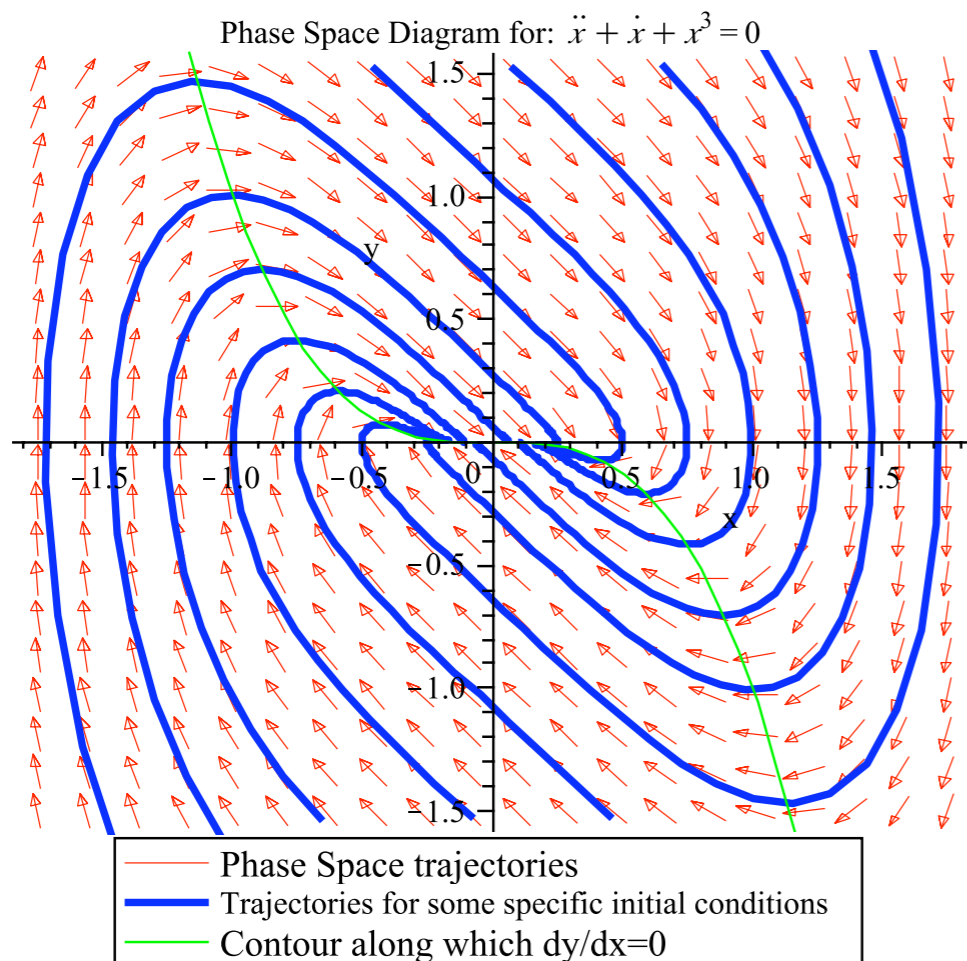
What about the higher order cases mentioned above?

- With the same considerations, for $\ddot{x} + \dot{x} + x^{2n} = 0$ we get: $x \sim \frac{1}{t^{2n-1}}$
- For $\ddot{x} + \dot{x} + x^{2n-1}$, however, there is no critical behavior.

Higher Order Terms and Exponents

What about the higher order cases mentioned above?

- With the same considerations, for $\ddot{x} + \dot{x} + x^{2n} = 0$ we get: $x \sim \frac{1}{t^{2n-1}}$
- For $\ddot{x} + \dot{x} + x^{2n-1}$, however, there is no critical behavior.



Outline

- The inflationary paradigm - reminder
- Large field and small field inflation
- Inflection point inflation (IPI)
- Phase transition (PT) in IPI
- Generalizations of the PT phenomenon
- Analytic discussion
- **Somewhat different PT in a stringy IPI model**

Similar Phase Transition in a String Theory Model

Similar Phase Transition in a String Theory Model

- Previous scenarios dealt with time-independent IPI.

Similar Phase Transition in a String Theory Model

- Previous scenarios dealt with time-independent IPI.
- Recently, a stringy time-dependent mechanism was introduced in order to overcome the overshoot problem in models of IPI. Its equations of motion are:

Similar Phase Transition in a String Theory Model

- Previous scenarios dealt with time-independent IPI.
- Recently, a stringy time-dependent mechanism was introduced in order to overcome the overshoot problem in models of IPI. Its equations of motion are:

$$\begin{aligned}3H^2 &= \frac{1}{2}\dot{\phi}^2 + V_{static} + V_{dynamic}, \\ \dot{n} &= -3Hn, \\ \ddot{\phi} + 3H\dot{\phi} &= -\frac{d}{d\phi}(V_{static} + V_{dynamic})\end{aligned}$$

Similar Phase Transition in a String Theory Model

- Previous scenarios dealt with time-independent IPI.
- Recently, a stringy time-dependent mechanism was introduced in order to overcome the overshoot problem in models of IPI. Its equations of motion are:

$$3H^2 = \frac{1}{2}\dot{\phi}^2 + V_{static} + V_{dynamic},$$

$$\dot{n} = -3Hn,$$

$$\ddot{\phi} + 3H\dot{\phi} = -\frac{d}{d\phi}(V_{static} + V_{dynamic})$$

- V_{static} is a small field potential (according to the first categorization) with an inflection point.

Similar Phase Transition in a String Theory Model

- Previous scenarios dealt with time-independent IPI.
- Recently, a stringy time-dependent mechanism was introduced in order to overcome the overshoot problem in models of IPI. Its equations of motion are:

$$3H^2 = \frac{1}{2}\dot{\phi}^2 + V_{static} + V_{dynamic},$$

$$\dot{n} = -3Hn,$$

$$\ddot{\phi} + 3H\dot{\phi} = -\frac{d}{d\phi}(V_{static} + V_{dynamic})$$

- V_{static} is a small field potential (according to the first categorization) with an inflection point.
- Particle with mass $\frac{dV_{static}}{d\phi} \frac{dM}{d\phi} < 0$ induces the time-dependent $V_{dynamic}$

String Theory IPI

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

$$\frac{1}{16\pi G_s} \int d^s x \sqrt{g_s} R_s \Rightarrow \frac{c}{16\pi G_s} \int d^4 x \sqrt{g_4} R_4 L^d$$

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

$$\frac{1}{16\pi G_s} \int d^s x \sqrt{g_s} R_s \Rightarrow \frac{c}{16\pi G_s} \int d^4 x \sqrt{g_4} R_4 L^d$$

- and rescale the metric:

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

$$\frac{1}{16\pi G_s} \int d^s x \sqrt{g_s} R_s \Rightarrow \frac{c}{16\pi G_s} \int d^4 x \sqrt{g_4} R_4 L^d$$

- and rescale the metric: $g_{4\mu\nu} \rightarrow g_{E\mu\nu} = (L/L_0)^d g_{4\mu\nu}$

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

$$\frac{1}{16\pi G_s} \int d^s x \sqrt{g_s} R_s \Rightarrow \frac{c}{16\pi G_s} \int d^4 x \sqrt{g_4} R_4 L^d$$

- and rescale the metric: $g_{4\mu\nu} \rightarrow g_{E\mu\nu} = (L/L_0)^d g_{4\mu\nu}$
- Finally, we reach the action:

String Theory IPI

Focus on modular inflation, other moduli besides inflaton assumed stabilized.

- We work in the traditional setup with a compact manifold M of dimension $d=6$. For simplicity, we assume: $\text{Vol}_M \propto L^d$. L will be our inflaton.
- We transfer to the Einstein frame, where the kinetic term for L does not mix with the kinetic term of the graviton, which ensures that the potential we find for L can be interpreted in the standard way:

$$\frac{1}{16\pi G_s} \int d^s x \sqrt{g_s} R_s \Rightarrow \frac{c}{16\pi G_s} \int d^4 x \sqrt{g_4} R_4 L^d$$

- and rescale the metric: $g_{4\mu\nu} \rightarrow g_{E\mu\nu} = (L/L_0)^d g_{4\mu\nu}$

- Finally, we reach the action: $S_1 = \frac{cL_0^d}{16\pi G_s} \int d^4 x \sqrt{g_E} R_E$

Contributions to the Potential

Contributions to the Potential

Assuming a compactification on a manifold M of radius L , contributions to the inflaton potential can arise from:

Contributions to the Potential

Assuming a compactification on a manifold M of radius L , contributions to the inflaton potential can arise from:

- **(3+p)-branes:** wrap regular $4D + p$ cycles in M . Have the following action:

$$N_{p+3} T_{3+p} \int d^4x \sqrt{g_4} L^p$$

Contributions to the Potential

Assuming a compactification on a manifold M of radius L , contributions to the inflaton potential can arise from:

- **(3+p)-branes:** wrap regular $4D + p$ cycles in M . Have the following action:

$$N_{p+3} T_{3+p} \int d^4 x \sqrt{g_4} L^p$$

where N_{p+3} is the number of (3+p)-branes and T_{3+p} is their tension. Moving to the Einstein frame gives an extra factor of $(L_0/L)^{d/2}$ for each of the four non-compact directions and the potential becomes:

$$V_{3+p} = N_{3+p} T_{3+p} L_0^{2d} \frac{1}{L^{2d-p}}$$

Contributions to the Potential

Assuming a compactification on a manifold M of radius L , contributions to the inflaton potential can arise from:

- **(3+p)-branes:** wrap regular $4D + p$ cycles in M . Have the following action:

$$N_{p+3} T_{3+p} \int d^4 x \sqrt{g_4} L^p$$

where N_{p+3} is the number of (3+p)-branes and T_{3+p} is their tension. Moving to the Einstein frame gives an extra factor of $(L_0/L)^{d/2}$ for each of the four non-compact directions and the potential becomes:

$$V_{3+p} = N_{3+p} T_{3+p} L_0^{2d} \frac{1}{L^{2d-p}}$$

- **I-fluxes:** the relevant term for l -cycle fluxes in the $(4+d)$ -dimensional action, assuming N units of F_l flux, after moving to the Einstein frame, will yield:

$$\int d^s x \sqrt{g_s} c_l F_l^2 \quad \longrightarrow \quad V_{l-flux} = N_l^2 c_l L_0^{2d} \frac{1}{L^{d+2l}}$$

Contributions to the Potential

Contributions to the Potential

- The scalar field L is not the canonical dynamical variable we usually use when we discuss inflation. In order to use the popular interpretation for the scalar potential, we have to canonically normalize L by:

$$L = e^{\alpha\phi} \quad \text{with} \quad \alpha = \frac{1}{\sqrt{24}}$$

Contributions to the Potential

- The scalar field L is not the canonical dynamical variable we usually use when we discuss inflation. In order to use the popular interpretation for the scalar potential, we have to canonically normalize L by:
$$L = e^{\alpha\phi} \quad \text{with} \quad \alpha = \frac{1}{\sqrt{24}}$$
- Our inflaton is then the scalar field ϕ .

Contributions to the Potential

- The scalar field L is not the canonical dynamical variable we usually use when we discuss inflation. In order to use the popular interpretation for the scalar potential, we have to canonically normalize L by:
$$L = e^{\alpha\phi} \quad \text{with} \quad \alpha = \frac{1}{\sqrt{24}}$$
- Our inflaton is then the scalar field ϕ .

- Naturally, we search for a successful combination of these potentials. It is particularly useful to use a combination that has an inflection point. In order to do this we need to join three terms in the potential:

$$V = a_1 \exp(-j_1 \alpha \phi) + a_2 \exp(-j_2 \alpha \phi) + a_3 \exp(-j_3 \alpha \phi)$$

Contributions to the Potential

- The scalar field L is not the canonical dynamical variable we usually use when we discuss inflation. In order to use the popular interpretation for the scalar potential, we have to canonically normalize L by:
$$L = e^{\alpha\phi} \quad \text{with} \quad \alpha = \frac{1}{\sqrt{24}}$$
- Our inflaton is then the scalar field ϕ .

- Naturally, we search for a successful combination of these potentials. It is particularly useful to use a combination that has an inflection point. In order to do this we need to join three terms in the potential:

$$V = a_1 \exp(-j_1 \alpha \phi) + a_2 \exp(-j_2 \alpha \phi) + a_3 \exp(-j_3 \alpha \phi)$$

where the parameters are chosen to satisfy, without loss of generality:

$$j_1 > j_2 > j_3, \quad a_1, a_3 > 0 \quad \text{and} \quad a_2 < 0$$

Contributions to the Potential

- The scalar field L is not the canonical dynamical variable we usually use when we discuss inflation. In order to use the popular interpretation for the scalar potential, we have to canonically normalize L by:
$$L = e^{\alpha\phi} \quad \text{with} \quad \alpha = \frac{1}{\sqrt{24}}$$
- Our inflaton is then the scalar field ϕ .

- Naturally, we search for a successful combination of these potentials. It is particularly useful to use a combination that has an inflection point. In order to do this we need to join three terms in the potential:

$$V = a_1 \exp(-j_1 \alpha \phi) + a_2 \exp(-j_2 \alpha \phi) + a_3 \exp(-j_3 \alpha \phi)$$

where the parameters are chosen to satisfy, without loss of generality:

$$j_1 > j_2 > j_3, \quad a_1, a_3 > 0 \quad \text{and} \quad a_2 < 0$$

- Orientifolds have negative tension and therefore induce negative V_{3+p} . Thus, using V_{p+3} , V_{l-flux} we can construct such a potential, with $a_2 < 0$.

Time-Dependent Potential

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

- This is a natural solution to the overshoot problem, as can be seen below:

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

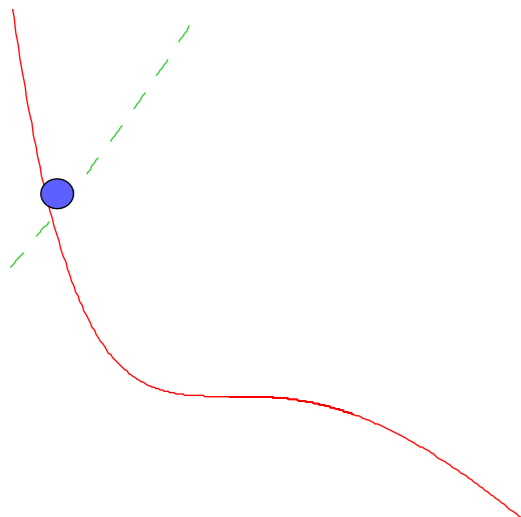
This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

- This is a natural solution to the overshoot problem, as can be seen below:



(a)

Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

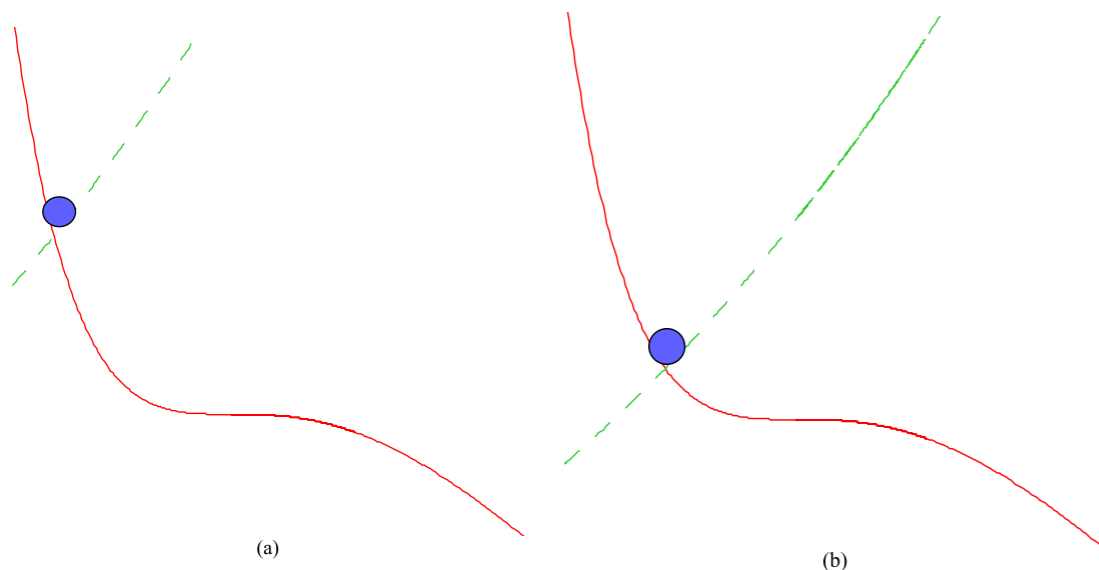
This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

- This is a natural solution to the overshoot problem, as can be seen below:



Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

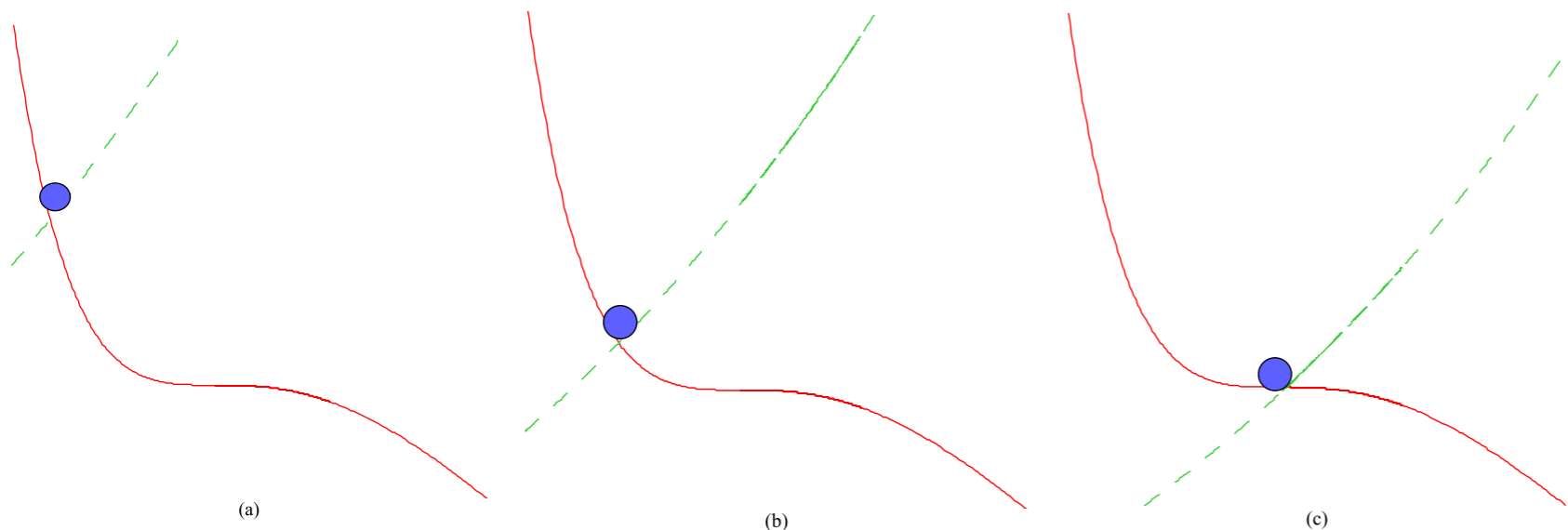
This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

- This is a natural solution to the overshoot problem, as can be seen below:



Time-Dependent Potential

- We focus on the non-perturbative states given by (0+p)-branes (branes that wrap p cycles in M and are point-like objects in the four dimensional uncompactified space-time). Their mass in the Einstein frame is:

$$m_{0+p} = T_{0+p} L^p \left(\frac{L_0}{L} \right)^{d/2}$$

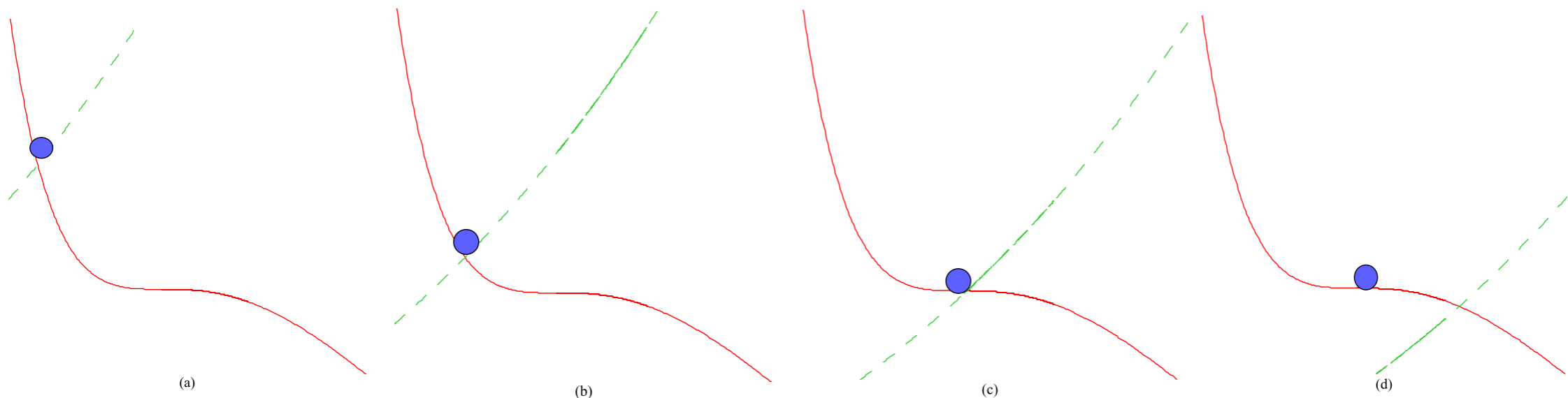
This leads to:

$$V_{0+p} = n_{0+p} T_{0+p} L_0^3 L^{p-3}$$

Which is a potential term which blow up as $L \rightarrow \infty$ and turns into the term:

$$V_{dynamic} = n(t) \exp(3\alpha\phi)$$

- This is a natural solution to the overshoot problem, as can be seen below:



Phase Transition

Phase Transition

- Indeed, for different values of the inflection point, we find an initial density that is big enough to slow down the inflaton so that inflation occurs.

$L_{inflection} \setminus n_0$	$1.5e - 05$	0.000315	0.00081	0.00541	0.099035
2	0.46215	0.46474	0.46909	0.51401	51130.0048
5	0.42172	0.45187	0.51436	41.6388	∞
8	0.42516	0.89218	44.8478	∞	∞
10	0.43725	53.3611	∞	∞	∞
20	384.1207	∞	∞	∞	∞

Phase Transition

- Indeed, for different values of the inflection point, we find an initial density that is big enough to slow down the inflaton so that inflation occurs.

$L_{inflection} \backslash n_0$	$1.5e - 05$	0.000315	0.00081	0.00541	0.099035
2	0.46215	0.46474	0.46909	0.51401	51130.0048
5	0.42172	0.45187	0.51436	41.6388	∞
8	0.42516	0.89218	44.8478	∞	∞
10	0.43725	53.3611	∞	∞	∞
20	384.1207	∞	∞	∞	∞

- The surprising feature here is that this value is critical. For initial conditions above it, inflation never ends. It is a similar phase transition to the one above.

Phase Transition

- Indeed, for different values of the inflection point, we find an initial density that is big enough to slow down the inflaton so that inflation occurs.

$L_{inflection} \backslash n_0$	$1.5e - 05$	0.000315	0.00081	0.00541	0.099035
2	0.46215	0.46474	0.46909	0.51401	51130.0048
5	0.42172	0.45187	0.51436	41.6388	∞
8	0.42516	0.89218	44.8478	∞	∞
10	0.43725	53.3611	∞	∞	∞
20	384.1207	∞	∞	∞	∞

- The surprising feature here is that this value is critical. For initial conditions above it, inflation never ends. It is a similar phase transition to the one above.
- In addition, we also see scaling behavior as the critical n_c is approached, again with an integer critical exponent of -1.

Conclusions

Conclusions

- The efficiency of the attractor mechanism in IPI models varies in a discontinuous fashion as we vary various parameters continuously.

Conclusions

- The efficiency of the attractor mechanism in IPI models varies in a discontinuous fashion as we vary various parameters continuously.
- The parameter space of these models can be divided into two regions.
 - In the small field region, N depends on the initial condition and in order to obtain a large N the initial condition generally has to be fine tuned.
 - In the large field region the efficiency of the attractor mechanism is maximized and all non-singular initial conditions yield the same N .

Conclusions

- The efficiency of the attractor mechanism in IPI models varies in a discontinuous fashion as we vary various parameters continuously.
- The parameter space of these models can be divided into two regions.
 - In the small field region, N depends on the initial condition and in order to obtain a large N the initial condition generally has to be fine tuned.
 - In the large field region the efficiency of the attractor mechanism is maximized and all non-singular initial conditions yield the same N .
- The surprising aspects of our findings are:
 - (I) The transition between the two regions happens at *finite* values of the parameters that define the potential.
 - (II) In some cases critical behavior takes place at the transition between the two regions.